Minimax Forward and Backward Learning of Evolving Tasks with Performance Guarantees

Basque Center for Applied Mathematics-BCAM

Verónica Álvarez, valvarez@bcamath.org
Santiago Mazuelas, smazuelas@bcamath.org
Jose A. Lozano, jlozano@bcamath.org







1910







































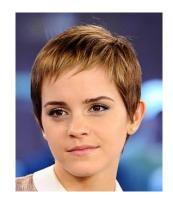














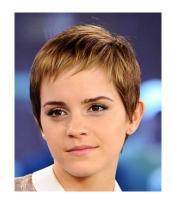


































Knowledge gaps

Concept drift adaptation techniques are designed for evolving tasks but only aim to learn the last task in the sequence

Continual learning techniques aim to learn the sequence of tasks but are not designed for evolving tasks

Knowledge gaps

Concept drift adaptation techniques are designed for evolving tasks but only aim to learn the last task in the sequence

Continual learning techniques aim to learn the sequence of tasks but are not designed for evolving tasks

Key contributions

Adapt to evolving tasks

Effectively exploit forward and backward learning

Provide performance guarantees and analytically characterize the increase in ESS

Incremental minimax risk classifiers (IMRCs)

Uncertainty set

$$\mathcal{U}_{j}^{\rightleftharpoons k} = \{ p \in \Delta(\mathcal{X} \times \mathcal{Y}) : |\mathbb{E}_{p} \{ \Phi(x, y) \} - \boldsymbol{\tau}_{j}^{\rightleftharpoons k} | \leq \boldsymbol{\lambda}_{j}^{\rightleftharpoons k} \}$$

where $\Phi: \mathcal{X} imes \mathcal{Y} o \mathbb{R}^m$ is a feature mapping

 $au_j^{
ightharpoonup k}$ is the mean vector of expectation estimate

 $\lambda_j^{
ightharpoonup k}$ is a confidence vector

Incremental minimax risk classifiers (IMRCs)

Uncertainty set

$$\mathcal{U}_{j}^{\rightleftharpoons k} = \{ p \in \Delta(\mathcal{X} \times \mathcal{Y}) : |\mathbb{E}_{p} \{ \Phi(x, y) \} - \boldsymbol{\tau}_{j}^{\rightleftharpoons k} | \leq \boldsymbol{\lambda}_{j}^{\rightleftharpoons k} \}$$

where $\Phi: \mathcal{X} \times \mathcal{Y} \to \mathbb{R}^m$ is a feature mapping

 $oldsymbol{ au}_j^{
ightharpoonup k}$ is the mean vector of expectation estimate

 $\lambda_i^{\rightleftharpoons k}$ is a confidence vector

Learning

$$R(\mathcal{U}_{j}^{\rightleftharpoons k}) = \min_{\mathbf{h} \in \mathrm{T}(\mathcal{X}, \mathcal{Y})} \max_{\mathbf{p} \in \mathcal{U}_{i}^{\rightleftharpoons k}} \ell(\mathbf{h}, \mathbf{p}) = \min_{\boldsymbol{\mu}} 1 - \boldsymbol{\tau}_{j}^{\rightleftharpoons k^{\mathrm{T}}} \boldsymbol{\mu} + \varphi(\boldsymbol{\mu}) + \boldsymbol{\lambda}_{j}^{\rightleftharpoons k^{\mathrm{T}}} |\boldsymbol{\mu}|$$

Prediction

$$\hat{y} \in \arg\max_{y \in \mathcal{Y}} \Phi(x, y)^{\mathrm{T}} \boldsymbol{\mu}_{j}^{*}$$

Single task learning

$$\boxed{\boldsymbol{\tau}_j} = \frac{1}{n_j} \sum_{i=1}^{n_j} \Phi(x_{j,i}, y_{j,i})$$

Single task learning

$$\tau_j = \frac{1}{n_j} \sum_{i=1}^{n_j} \Phi(x_{j,i}, y_{j,i})$$

Forward learning

$$oldsymbol{ au_j} = oldsymbol{ au_j} + rac{oldsymbol{s}_j}{oldsymbol{s}_{j-1}^{
ightharpoonup} + oldsymbol{s}_j + oldsymbol{s}_j + oldsymbol{d}_j^2 \left(oldsymbol{ au}_{j-1}^{
ightharpoonup} - oldsymbol{ au}_j
ight)$$

Single task learning

$$\boxed{\boldsymbol{\tau}_j} = \frac{1}{n_j} \sum_{i=1}^{n_j} \Phi(x_{j,i}, y_{j,i})$$

Forward learning

$$oldsymbol{ au_j} = oldsymbol{ au_j} + rac{oldsymbol{s_j}}{oldsymbol{s_{j-1}}^{
ightharpoonup} + oldsymbol{s_j}} ig(oldsymbol{ au_{j-1}}^{
ightharpoonup} - oldsymbol{ au_j}ig)$$

Single task learning

$$\tau_j = \frac{1}{n_j} \sum_{i=1}^{n_j} \Phi(x_{j,i}, y_{j,i})$$

Forward learning

$$oldsymbol{ au_j} = oldsymbol{ au_j} + rac{oldsymbol{s_j}}{oldsymbol{s_{j-1}}^{
ightharpoonup} + oldsymbol{s_j}} \left(oldsymbol{ au_{j-1}}^{
ightharpoonup} - oldsymbol{ au_j}
ight)$$

Forward and Backward learning

$$oldsymbol{ au}_{j}^{
ightharpoonup k} = oldsymbol{ au}_{j}^{
ightharpoonup k} + rac{oldsymbol{s}_{j}^{
ightharpoonup k}}{oldsymbol{s}_{i}^{
ightharpoonup k} + oldsymbol{s}_{j+1}^{
ightharpoonup k} + oldsymbol{d}_{j+1}^{
ightharpoonup k} + oldsymbol{d}_{j+1}^{
ightharpoonup k} - oldsymbol{ au}_{j}^{
ightharpoonup k} - oldsymbol{ au}_{j}^{
ightharpoonup k} - oldsymbol{ au}_{j}^{
ightharpoonup k} - oldsymbol{ au}_{j+1}^{
ightharpoonup k} - oldsymbol{ au}_{j}^{
ightharpoonup k} - oldsymbol{ au}_{j+1}^{
ightharpoonup k} - oldsymbol{ au}_{j}^{
ightharpoonup k} - oldsymbol{ au}_{j}^{
ightharpoonup k} - oldsymbol{ au}_{j}^{
ightharpoonup k} - oldsymbol{ au}_{j+1}^{
ightharpoonup k} - oldsymbol{ au}_{j}^{
ightharpoonup k} - oldsymbol{ au}_{j+1}^{
ightharpoonup k} - oldsymbol{ au}_{j+1}^{
ightharpoonup k} - oldsymbol{ au}_{j+1}^{
ightharpoonup k} - oldsymbol{ au}_{j}^{
i$$

$$R(\mathcal{U}_{j}^{\rightleftharpoons k}) \leq R_{j}^{\infty} + \frac{M(\kappa+1)\sqrt{2\log(2m/\delta)}}{\sqrt{\text{ESS}}} \|\boldsymbol{\mu}_{j}^{\infty}\|_{1}$$

$$R(\mathcal{U}_{j}^{\rightleftharpoons k}) \leq R_{j}^{\infty} + \frac{M(\kappa + 1)\sqrt{2\log(2m/\delta)}}{\sqrt{\text{ESS}}} \left\| \boldsymbol{\mu}_{j}^{\infty} \right\|_{1}$$

Single task learning

$$R(\mathcal{U}_j^{\rightleftharpoons k}) \leq R_j^\infty + \frac{M(\kappa+1)\sqrt{2\log{(2m/\delta)}}}{\sqrt{\mathrm{ESS}}} \left\|\boldsymbol{\mu}_j^\infty\right\|_1$$
 Single task learning
$$n_j / \frac{\|\boldsymbol{\sigma}_j^2\|_\infty}{\|\boldsymbol{\sigma}_j^2\|_\infty + n_{j-1}^{\rightharpoonup}\|\boldsymbol{d}_{j+1}^2\|_\infty}$$
 Forward learning

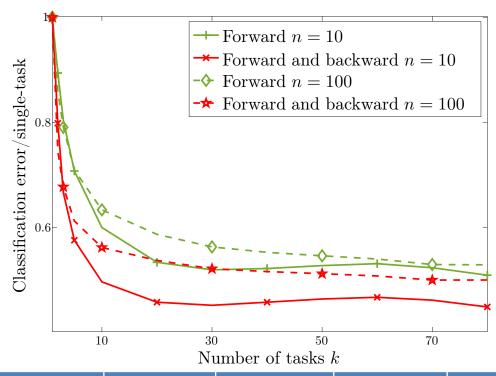
$$R(\mathcal{U}_{j}^{\rightleftharpoons k}) \leq R_{j}^{\infty} + \frac{M(\kappa + 1)\sqrt{2\log(2m/\delta)}}{\sqrt{\text{ESS}}} \|\boldsymbol{\mu}_{j}^{\infty}\|_{1}$$

Single task learning

Forward learning

Forward and Backward learning

Experimental results



Algorithm	Yearbook	I. Noise	DomainNet	UTKFaces	R. MNIST	CLEAR
GEM	.18 ± .03	.39 ± .08	.69 ± .05	.12 ± .00	$.36 \pm .06$.57 ± .10
MER	.16 ± .03	.17 ± .03	.38 ± .04	.17 ± .09	.37 ± .09	.10 ± .03
ELLA	.45 ± .01	.48 <u>+</u> .05	.67 ± .05	.19 ± .12	.48 ± .05	.61 ± .03
CL-MRC	.13 ± .04	.15 ± .03	.34 ± .06	.10 ± .01	.36 ± .01	.09 ± .03