

EXACT RECOVERY AND BREGMAN HARD CLUSTERING OF NODE-ATTRIBUTED STOCHASTIC BLOCK MODEL

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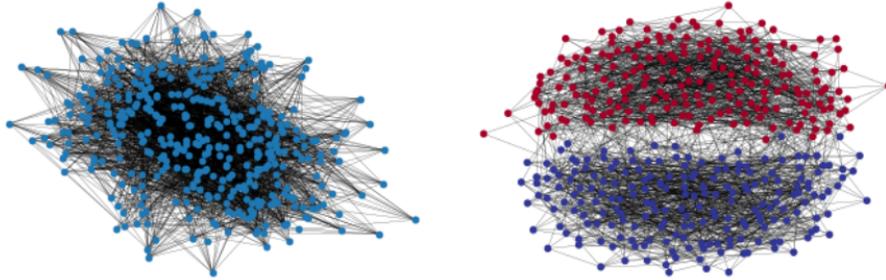
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GRAPH CLUSTERING WITH NODE ATTRIBUTES



Setup

- ▶ Observed data: Interactions between node pairs (network) and node attributes (features).
- ▶ Hidden data: Nodes are divided into clusters.

Main focus

- ▶ **Theoretical**: how much information is brought by the network and by the attributes?
- ▶ **Practical**: derive an algorithm that learns both from the *network* and from the *attributes*.
 - network: often sparse and possibly weighted;
 - attributes: a vector with discrete or continuous entries (or a mix of both).

NODE-ATTRIBUTED SBMS

- ▶ n nodes are divided into K latent blocks. We denote by $\mathbf{z} \in [K]^n$ the vector of the block (cluster) memberships, and we suppose that:
 - z_1, \dots, z_n are iid such that $\mathbb{P}(z_i = a) = \pi_a$.
- ▶ Pairwise interactions $(X_{ij})_{1 \leq i, j \leq n}$ and node attributes $(Y_i)_{1 \leq i \leq n}$ are independent conditionally on the blocks:
 - $f_{ab}(X_{ij})$: probability of observing an interaction X_{ij} between a node i in block a and a node j in block b ;
 - $h_a(Y_i)$: probability of observing an attribute Y_i for a node i in a block a .

Conditional distribution of the data (X, Y) given block memberships \mathbf{z} :

$$\mathbb{P}(X, Y | \mathbf{z}) = \prod_{1 \leq i < j \leq n} f_{z_i z_j}(X_{ij}) \prod_{i=1}^n h_{z_i}(Y_i).$$

How hard is it to recover \mathbf{z} based on the observation of X and Y ?

EXACT RECOVERY OF BLOCK MEMBERSHIPS

Denote by $D_t(f\|g) = \frac{1}{t-1} \log \int f^t g^{1-t}$ the *Rényi divergence* of order t between two pdf f and g . A key information-theoretic divergence is

$$I = \min_{\substack{a,b \in [K] \\ a \neq b}} \text{CH}(a, b). \quad (1.1)$$

where $\text{CH}(a, b) = \sup_{t \in (0,1)} (1-t) \left[\underbrace{\sum_{c=1}^K \pi_c D_t(f_{bc} \| f_{ac})}_{\text{information from the network}} + \underbrace{\frac{1}{n} D_t(h_b \| h_a)}_{\text{information from the attributes}} \right].$

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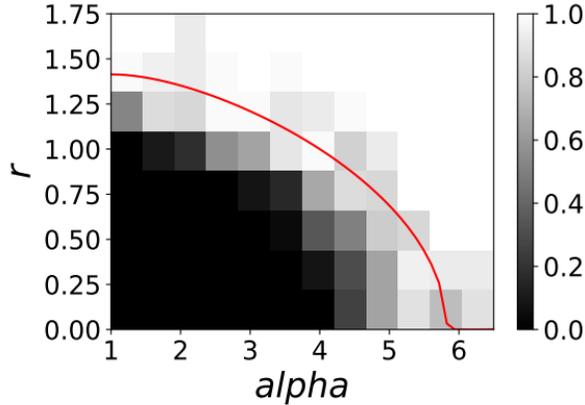
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Theorem 1

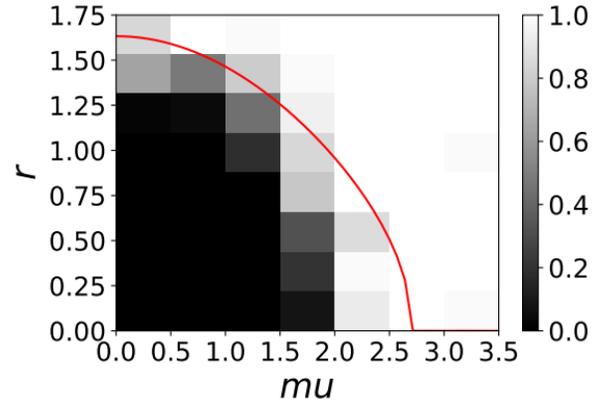
Suppose $K = \Theta(1)$ and $\pi_a > 0$ for all $a \in [K]$. Denote by a^*, b^* the two hardest blocks to distinguish, that is $\text{CH}(a^*, b^*) = I$. Suppose for all $t \in (0, 1)$, $\lim_{n \rightarrow \infty} \frac{n}{\log n} \text{CH}_t(a^*, b^*)$ exists and is strictly concave. Then the following holds:

- (i) exact recovery of z is information-theoretically impossible if $\lim_{n \rightarrow \infty} \frac{n}{\log n} I < 1$;
- (ii) exact recovery of z is information-theoretically possible if $\lim_{n \rightarrow \infty} \frac{n}{\log n} I > 1$.

NUMERICAL EXPERIMENTS



(a) Binary weights with Gaussian attributes



(b) zero-inflated Gaussian weights with Gaussian attributes.

Figure. Phase transition of exact recovery. Each pixel represents the empirical probability that Algorithm 1 succeeds at exactly recovering the clusters (over 50 runs), and the red curve shows the theoretical threshold.

(a) $n = 500$, $K = 2$, $f_{\text{in}} = \text{Ber}(\alpha n^{-1} \log n)$, $f_{\text{out}} = \text{Ber}(n^{-1} \log n)$. The attributes are 2d-spherical Gaussian with radius $(\pm r\sqrt{\log n}, 0)$ and identity covariance matrix.

(b) $n = 600$, $K = 3$, $f_{\text{in}} = (1 - \rho)\delta_0 + \rho \text{Nor}(\mu, 1)$, $f_{\text{out}} = (1 - \rho)\delta_0 + \rho \text{Nor}(0, 1)$ with $\rho = 5n^{-1} \log n$. The attributes are 2d-spherical Gaussian whose means are the vertices of a regular polygon on the circle of radius $r\sqrt{\log n}$.

CONCLUSION

In this presentation

Theoretical threshold for exact recovery of the community structure combines both the network and attribute information.

In the paper & poster

Algorithm that clusters sparse networks with weighted interactions and with node-attributes.

- ▶ We suppose the attributes are sampled from an *exponential family*;
- ▶ We suppose the network interactions are sampled from *zero-inflated exponential families*;
- ▶ We use the relationship between exponential families and *Bregman divergences* to derive an iterative algorithm based on *profile-likelihood maximisation*.