

# A self-supervised learning objective explains the *modular* organization of grid cells

Mikail Khona @KhonaMikail  
[\(mikail@mit.edu\)](mailto:(mikail@mit.edu))

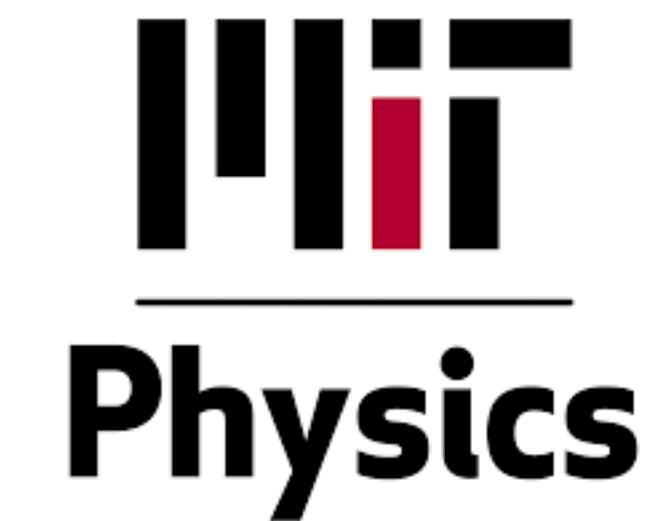
Rylan Schaeffer @RylanSchaeffer  
[\(rylanschaeffer@gmail.com\)](mailto:(rylanschaeffer@gmail.com))



K. LISA YANG  
ICoN CENTER

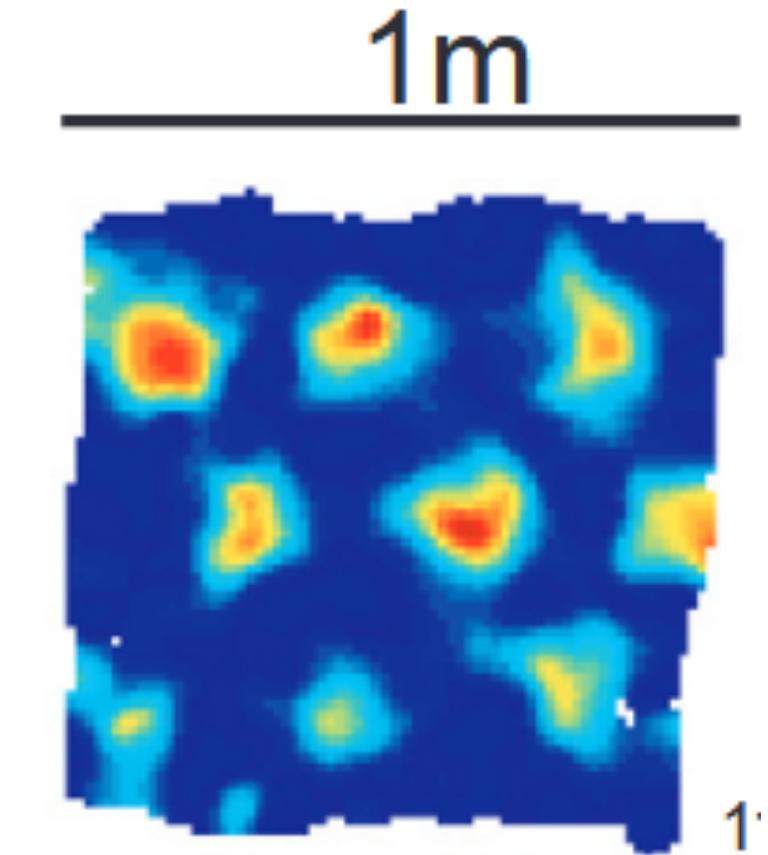


Stanford | ENGINEERING  
Computer Science

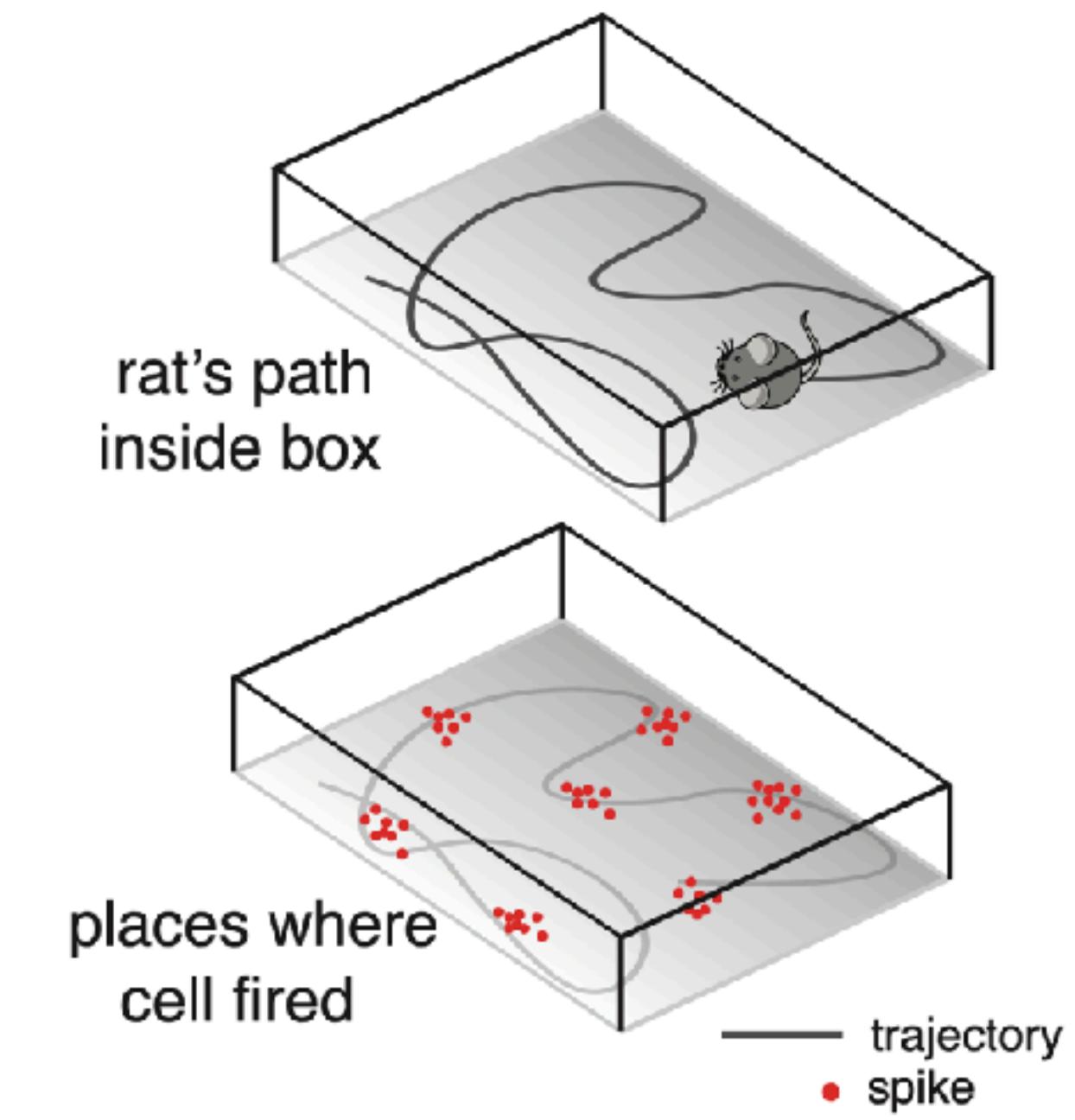
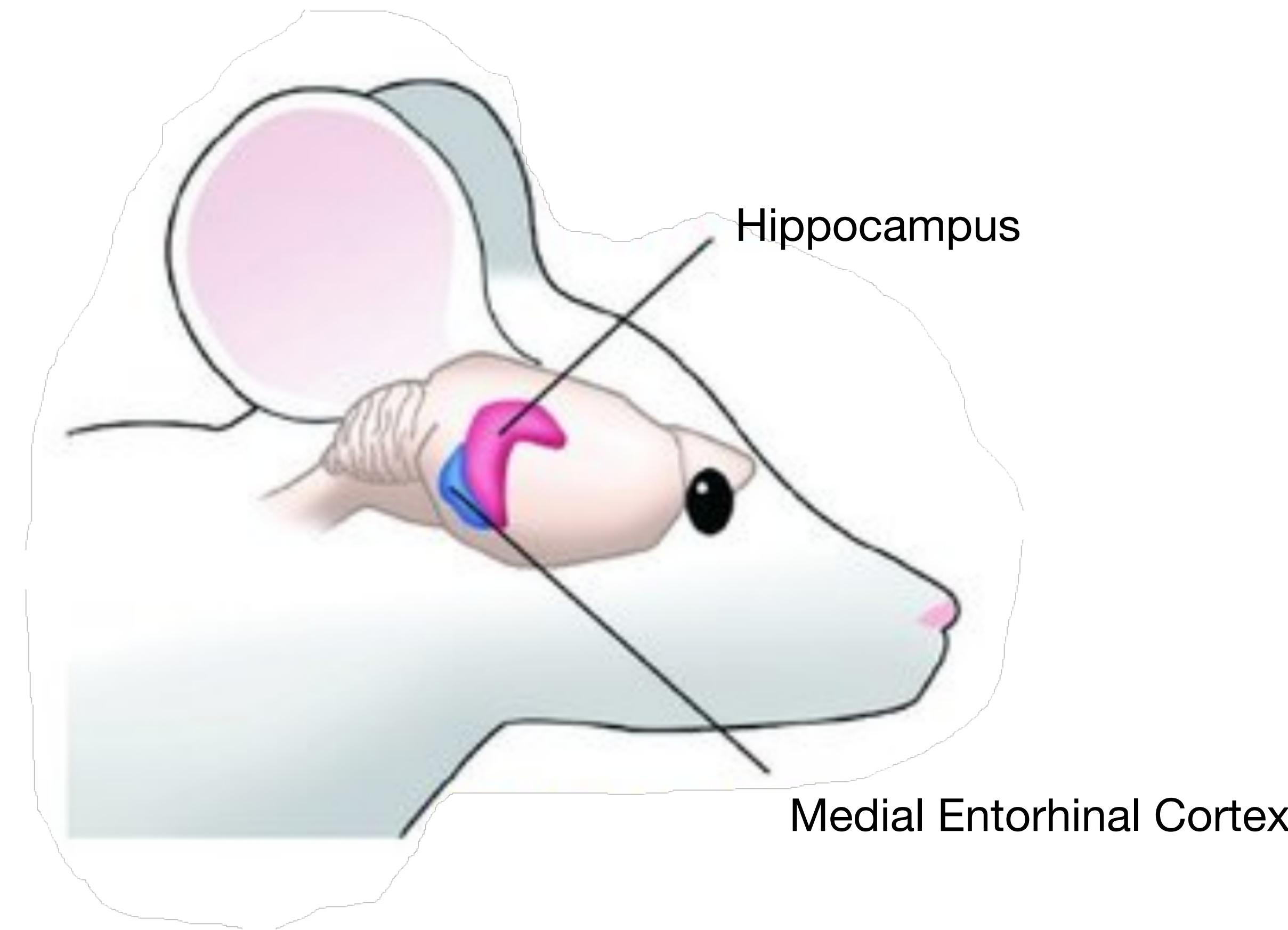


# The grid cell system in the MEC

- Grid cells in the medial Entorhinal Cortex (mEC) keep track of **allocentric location** modulo a hexagonal lattice.

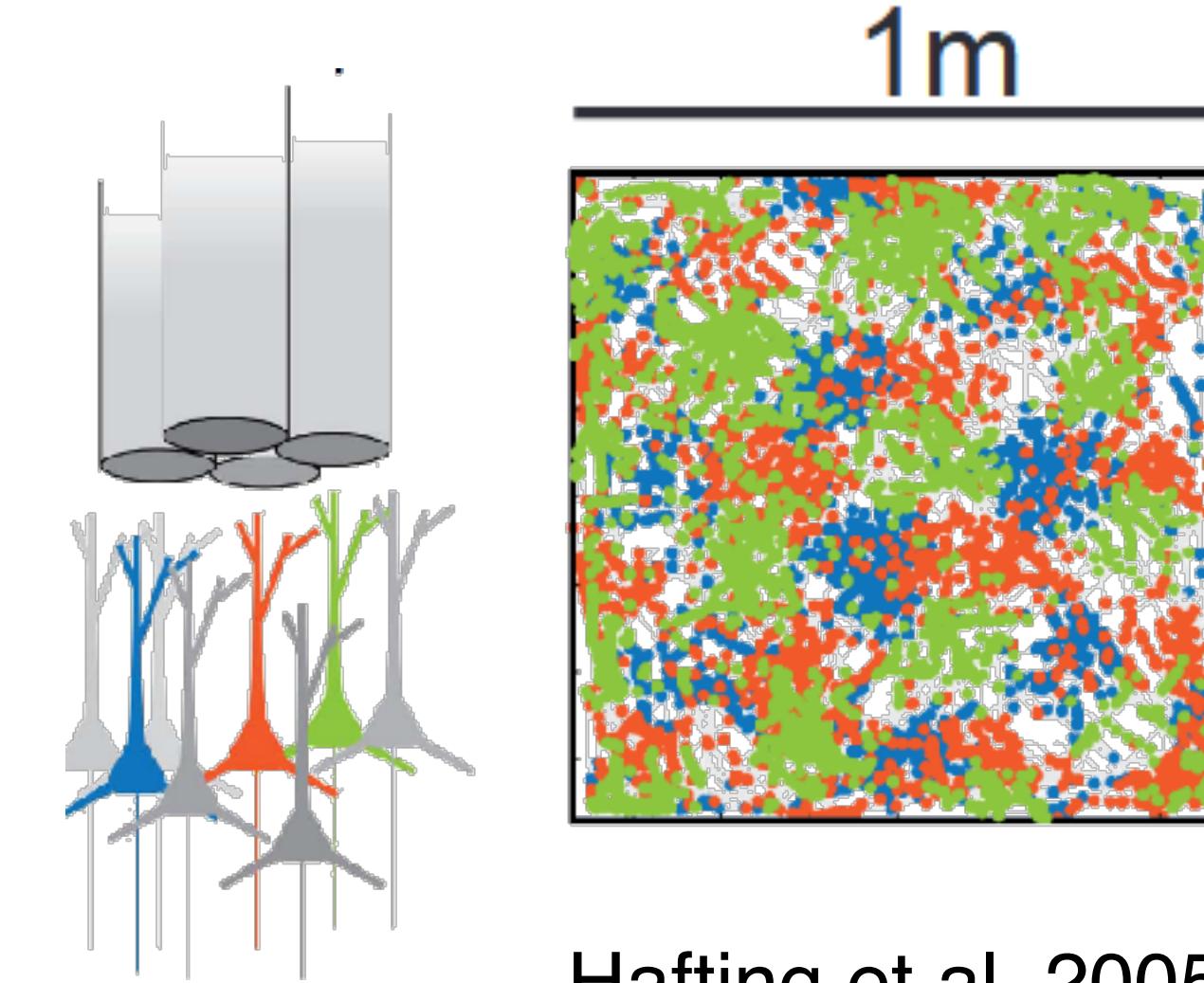


Hafting et al. 2005

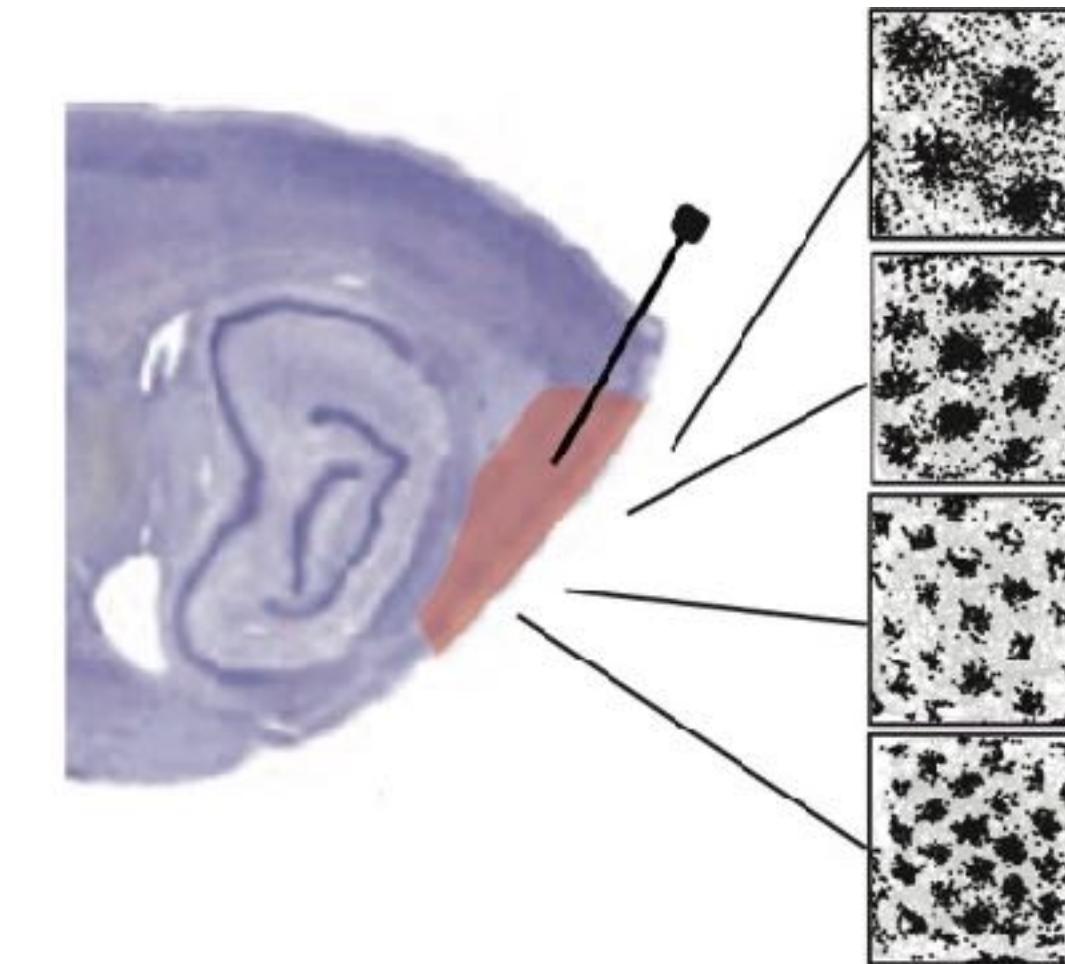
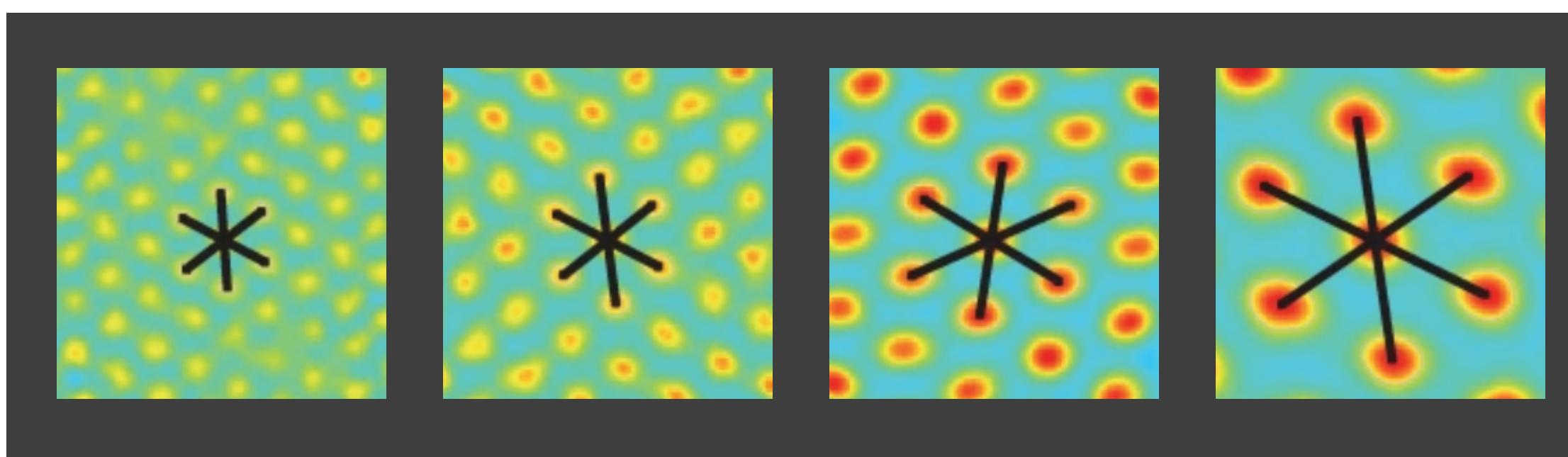


# The grid cell system in the MEC

- Grid cells in the medial Entorhinal Cortex (mEC) keep track of **allocentric location** modulo a hexagonal lattice.
- Different grid cells keep track of this information with respect to lattices of different phases and lattice spacings.
- Periodicity is arranged along dorso-ventral (DV) axis of mEC



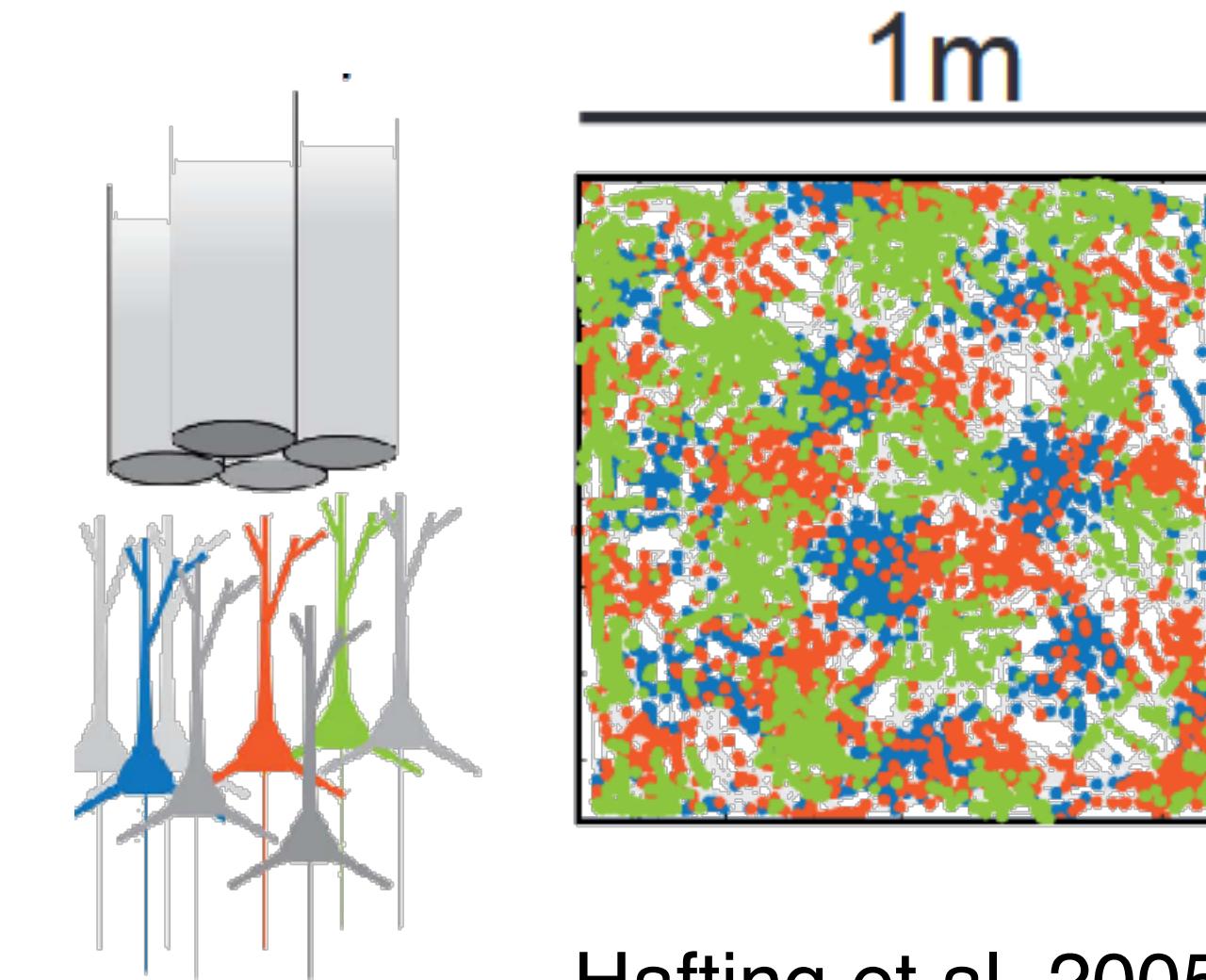
Hafting et al. 2005



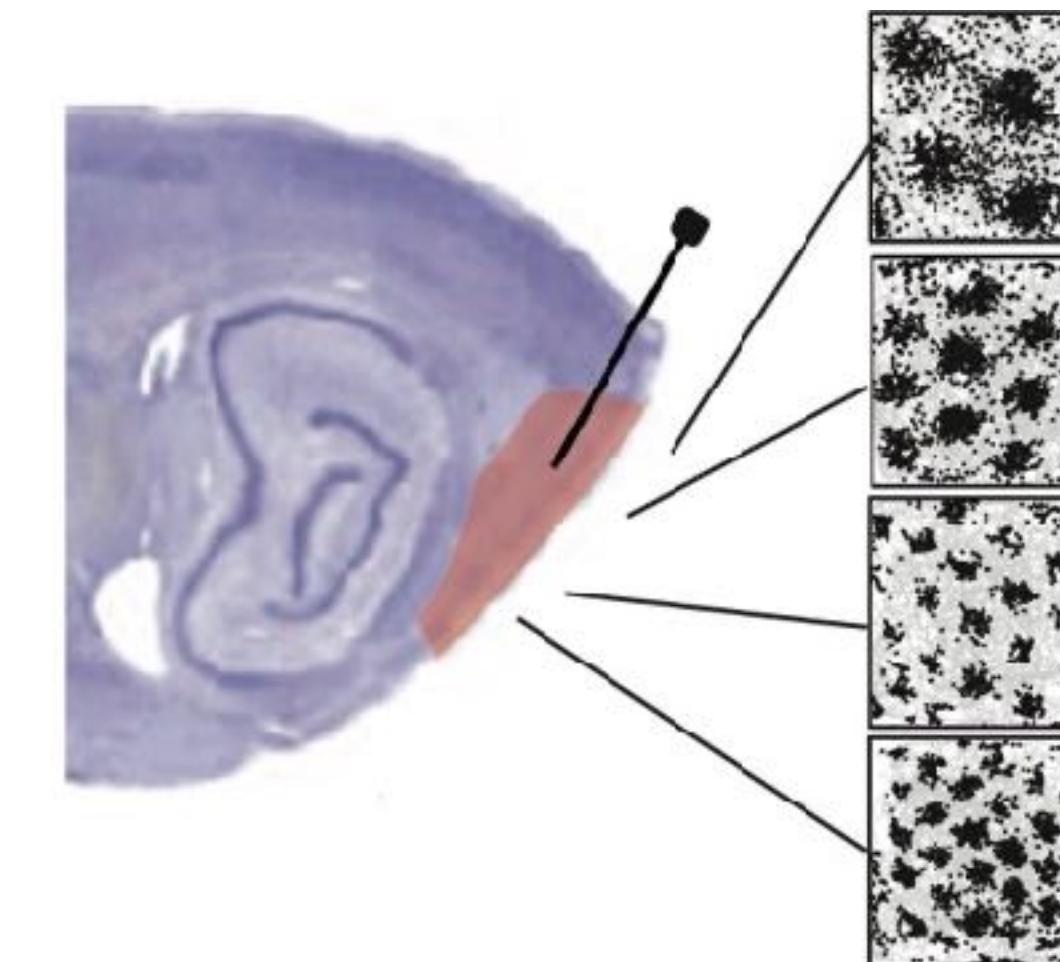
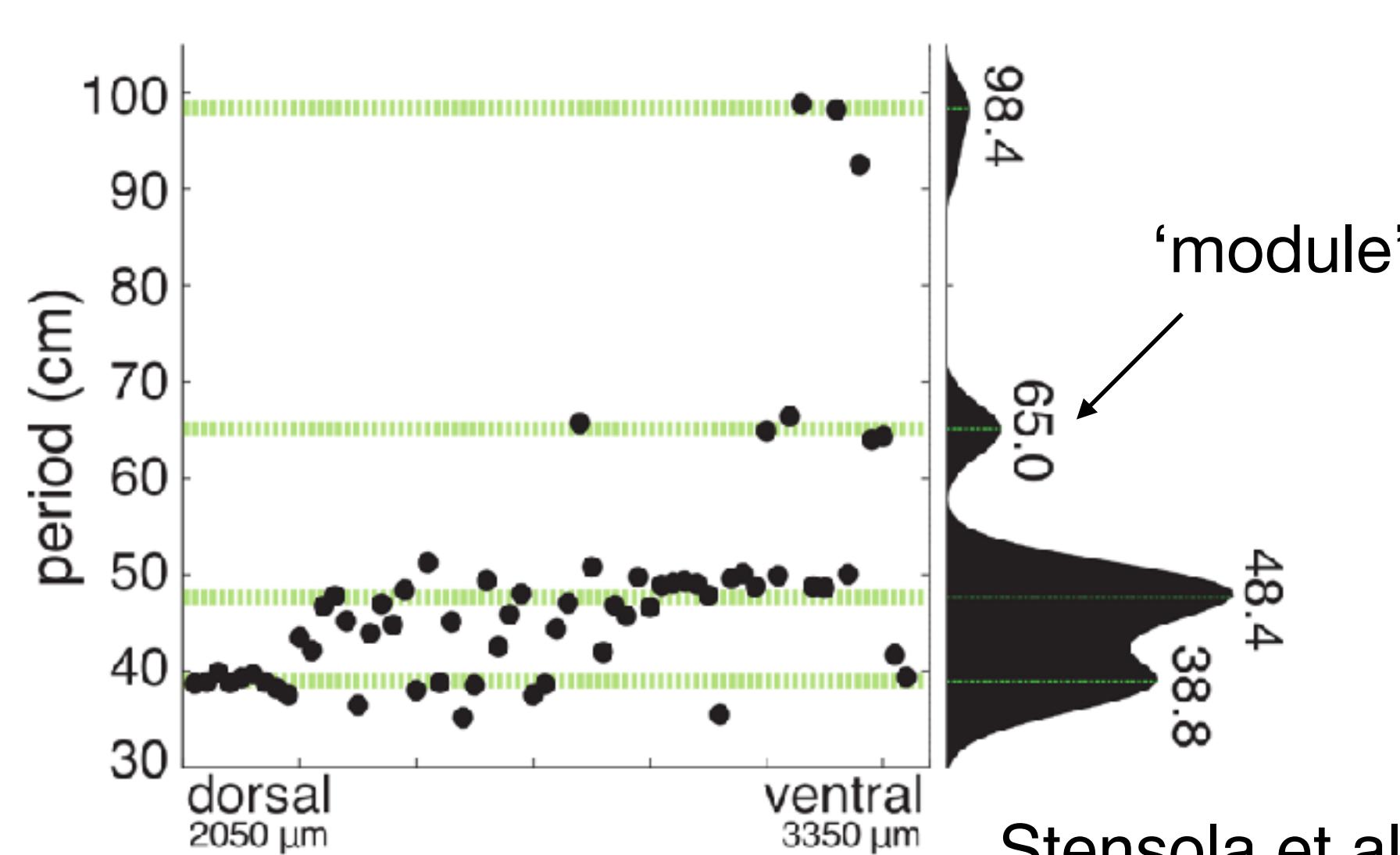
Stensola et al, The entorhinal grid map is discretized. Nature (2012)

# The grid cell system in the MEC

- Grid cells in the medial Entorhinal Cortex (mEC) keep track of **allocentric location** modulo a hexagonal lattice.
- Different grid cells keep track of this information with respect to lattices of different phases and lattice spacings.
- Periodicity is arranged along dorso-ventral (DV) axis of mEC

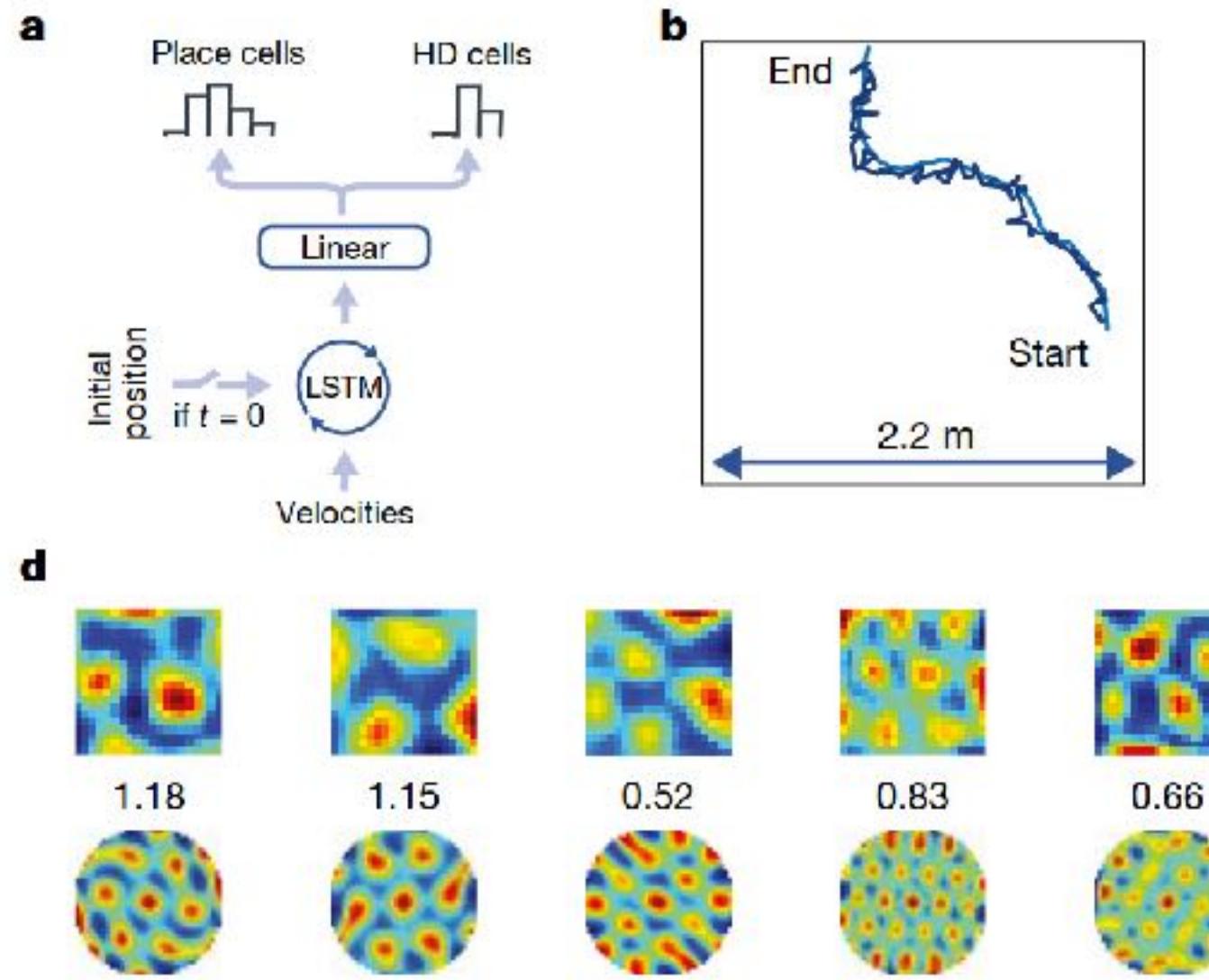


Hafting et al. 2005

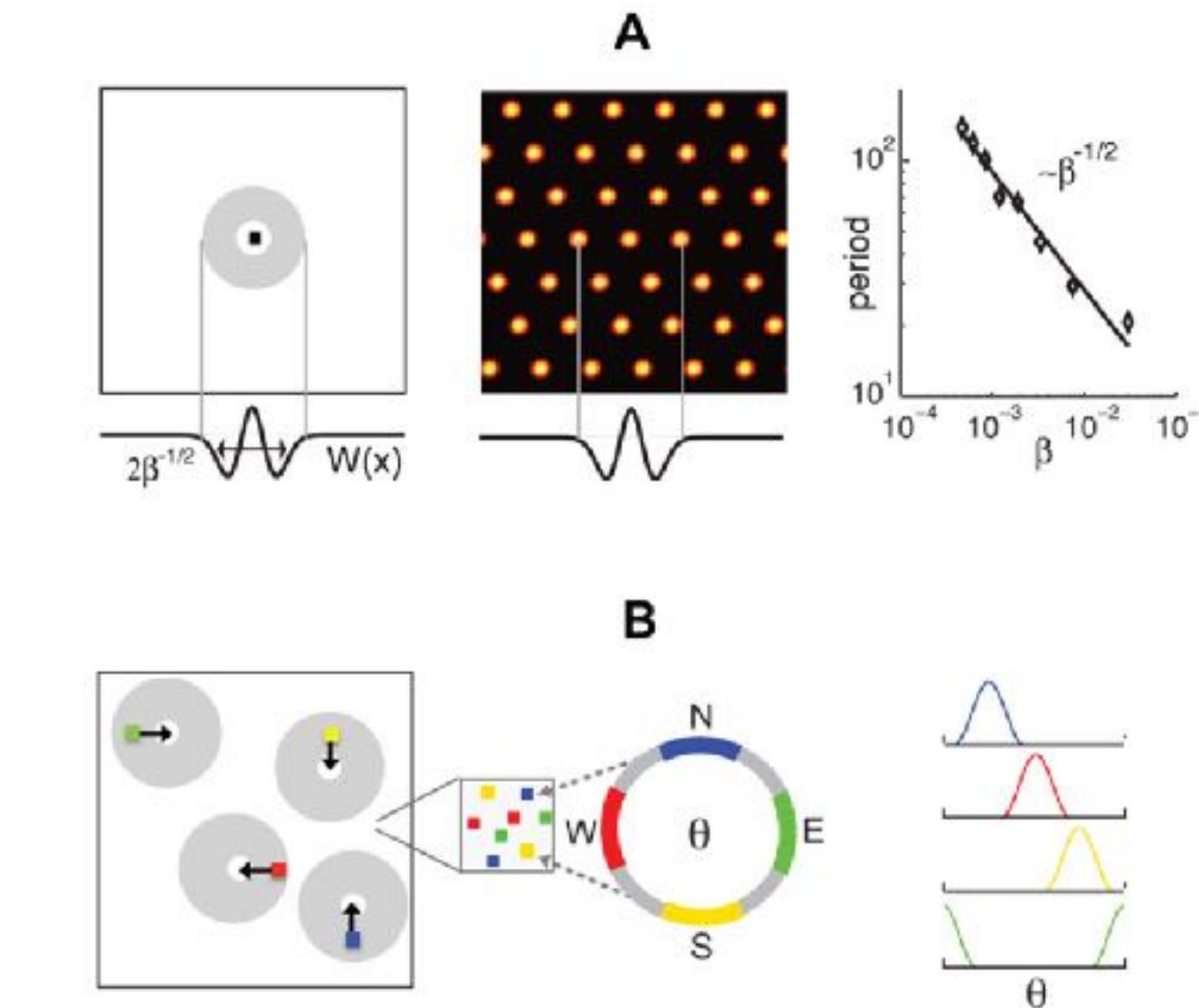


Stensola et al, The entorhinal grid map is discretized. Nature (2012)

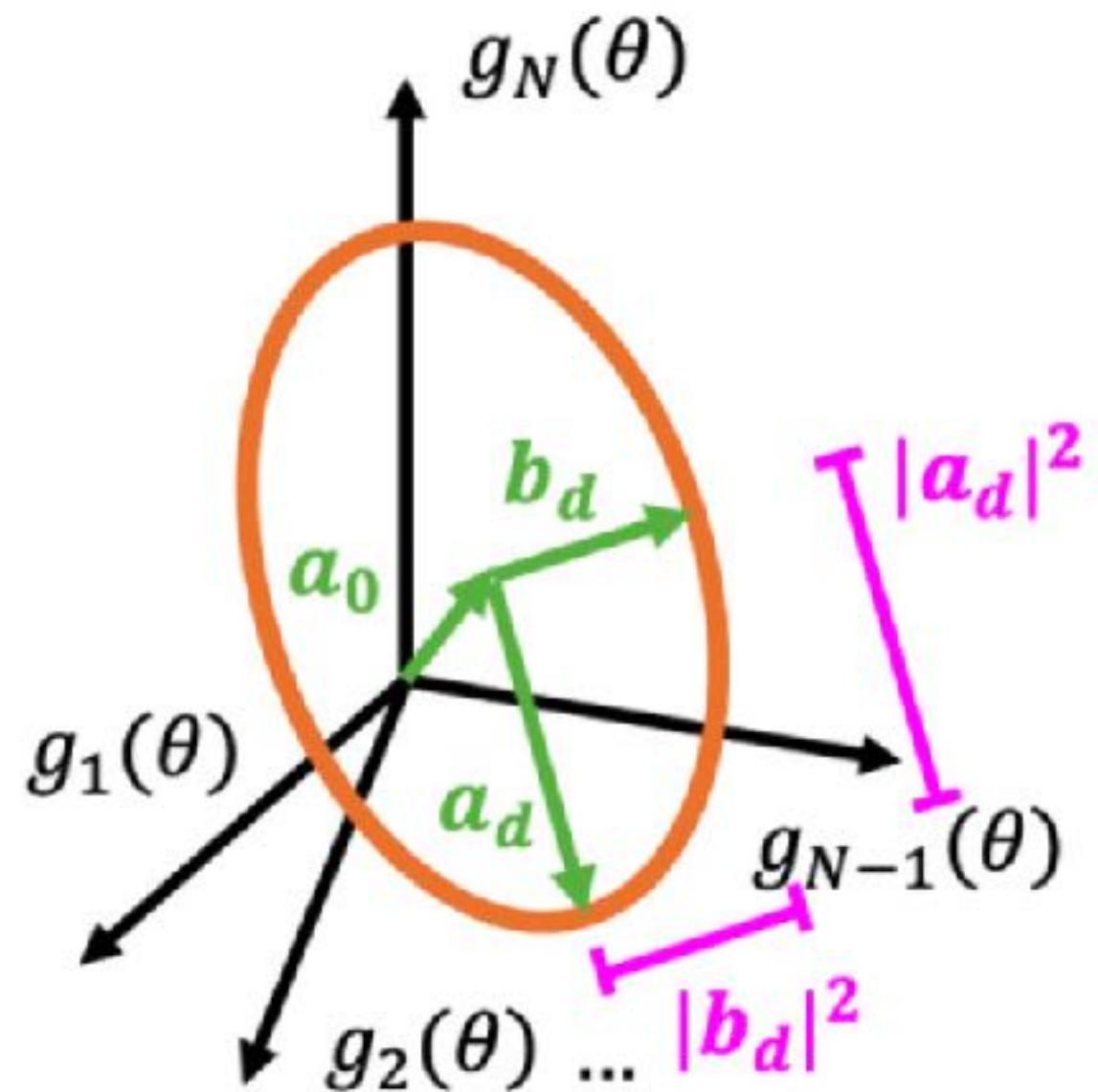
## Supervised learning



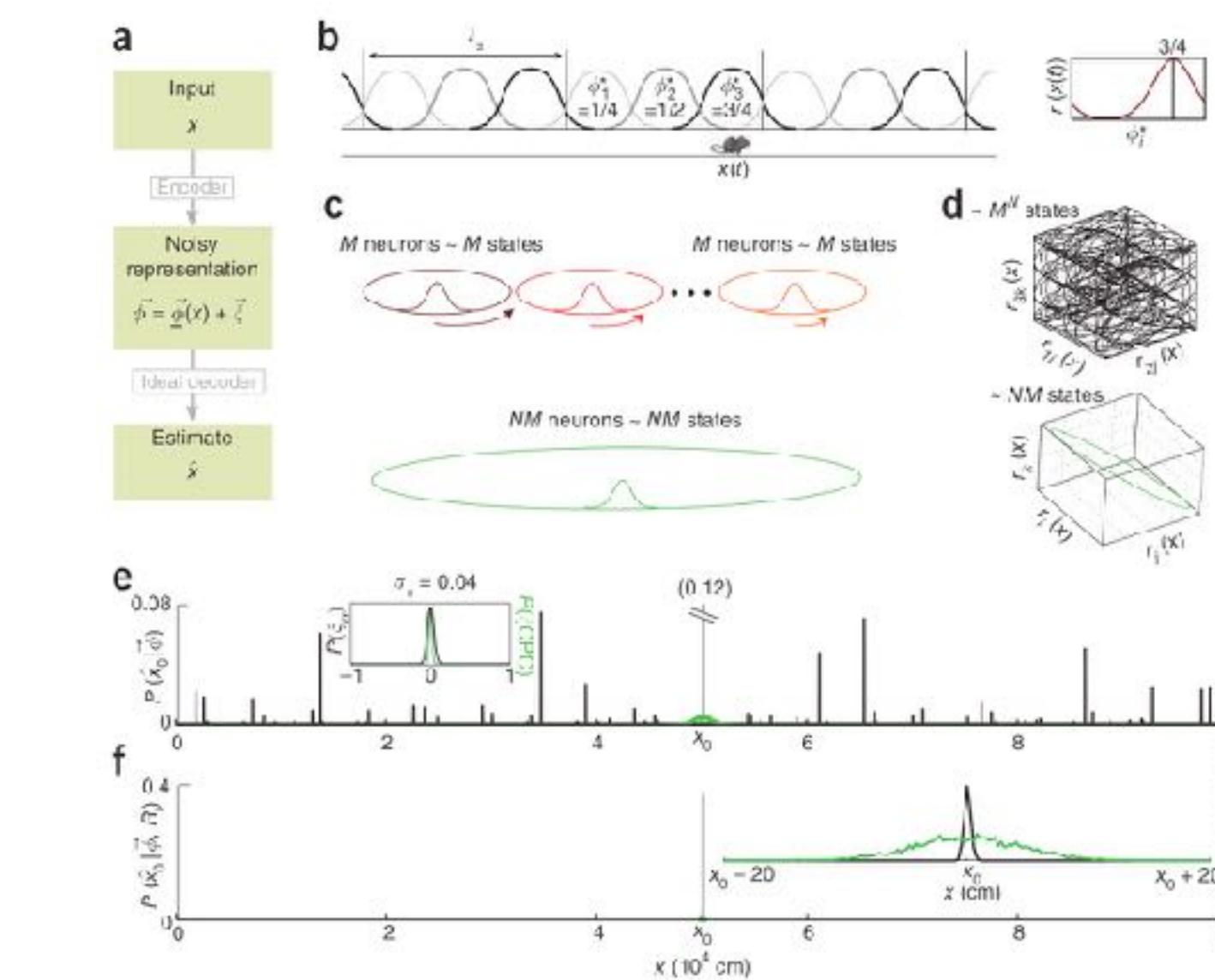
## Continuous attractors



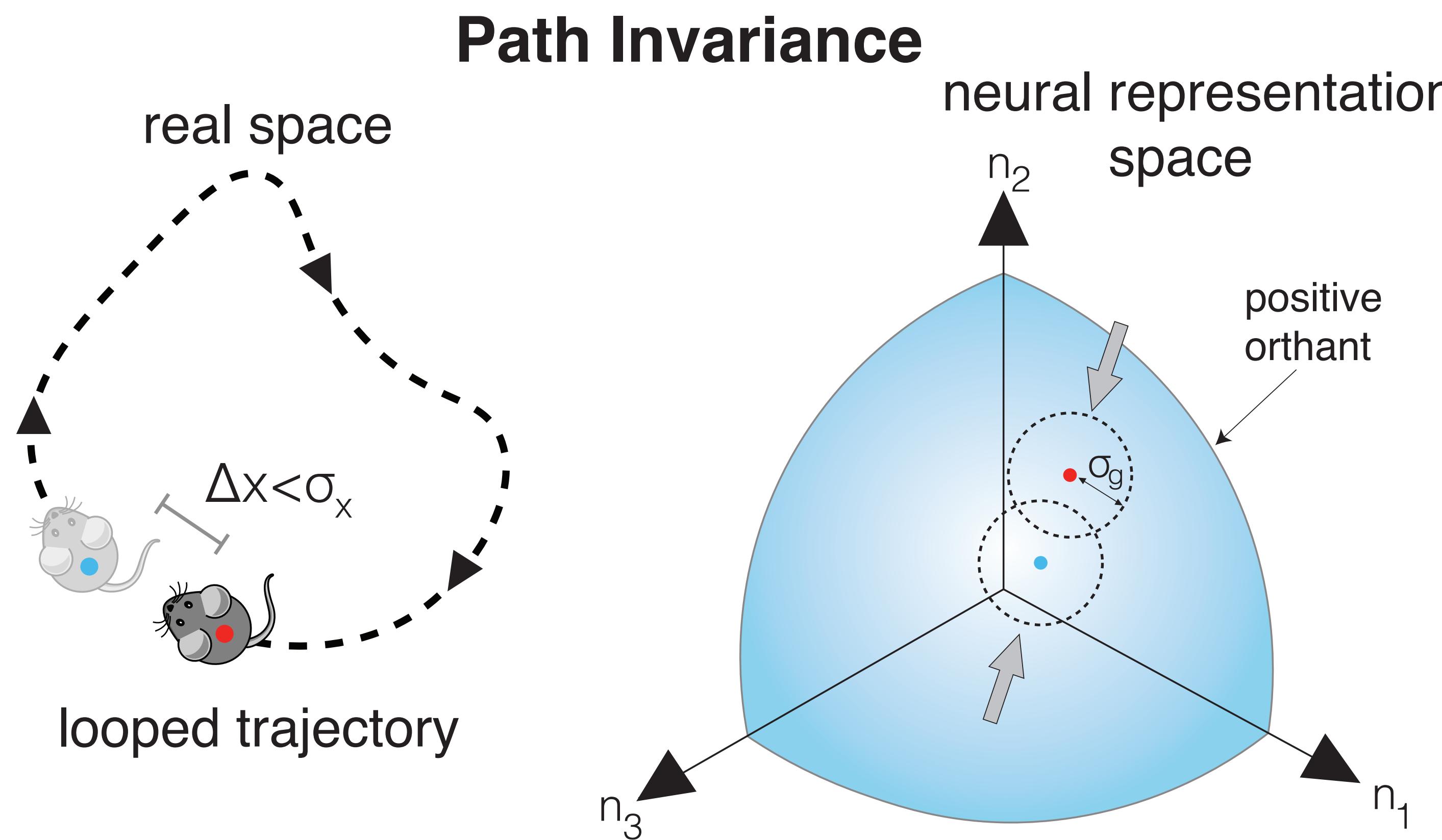
## Basis function optimization



## Coding theory



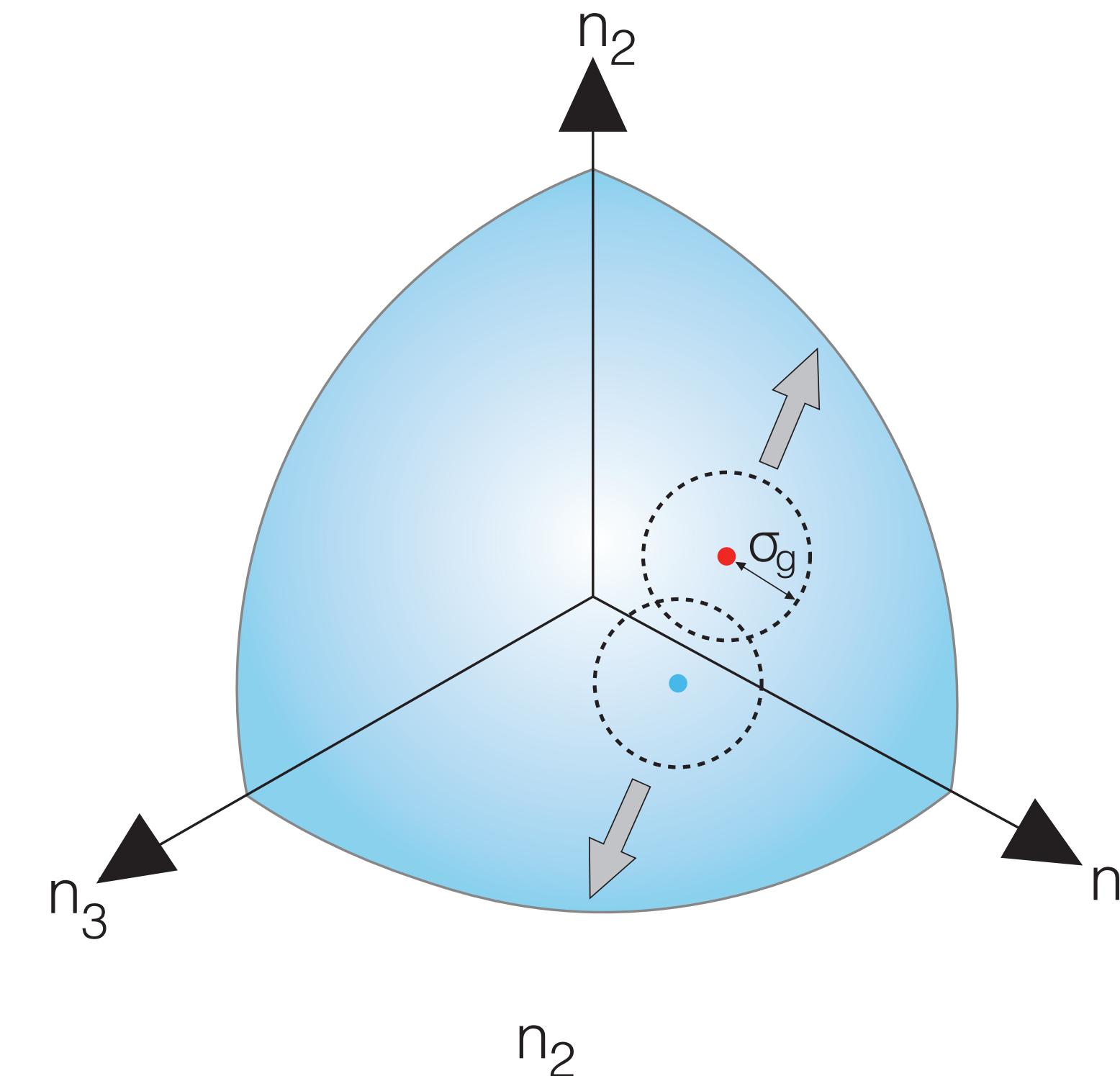
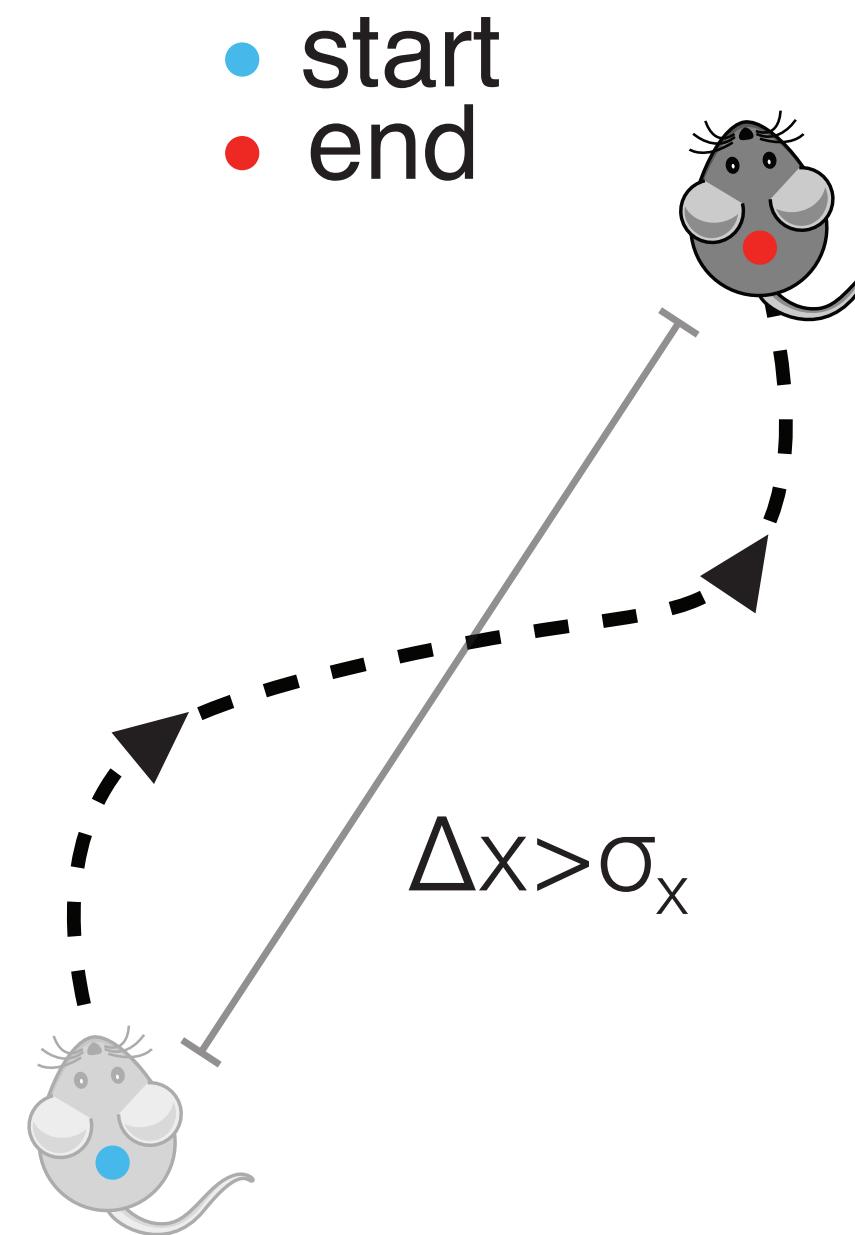
We can use these insights to formulate a self-supervised learning SSL problem



This ‘loop closure’ property is needed for path integration

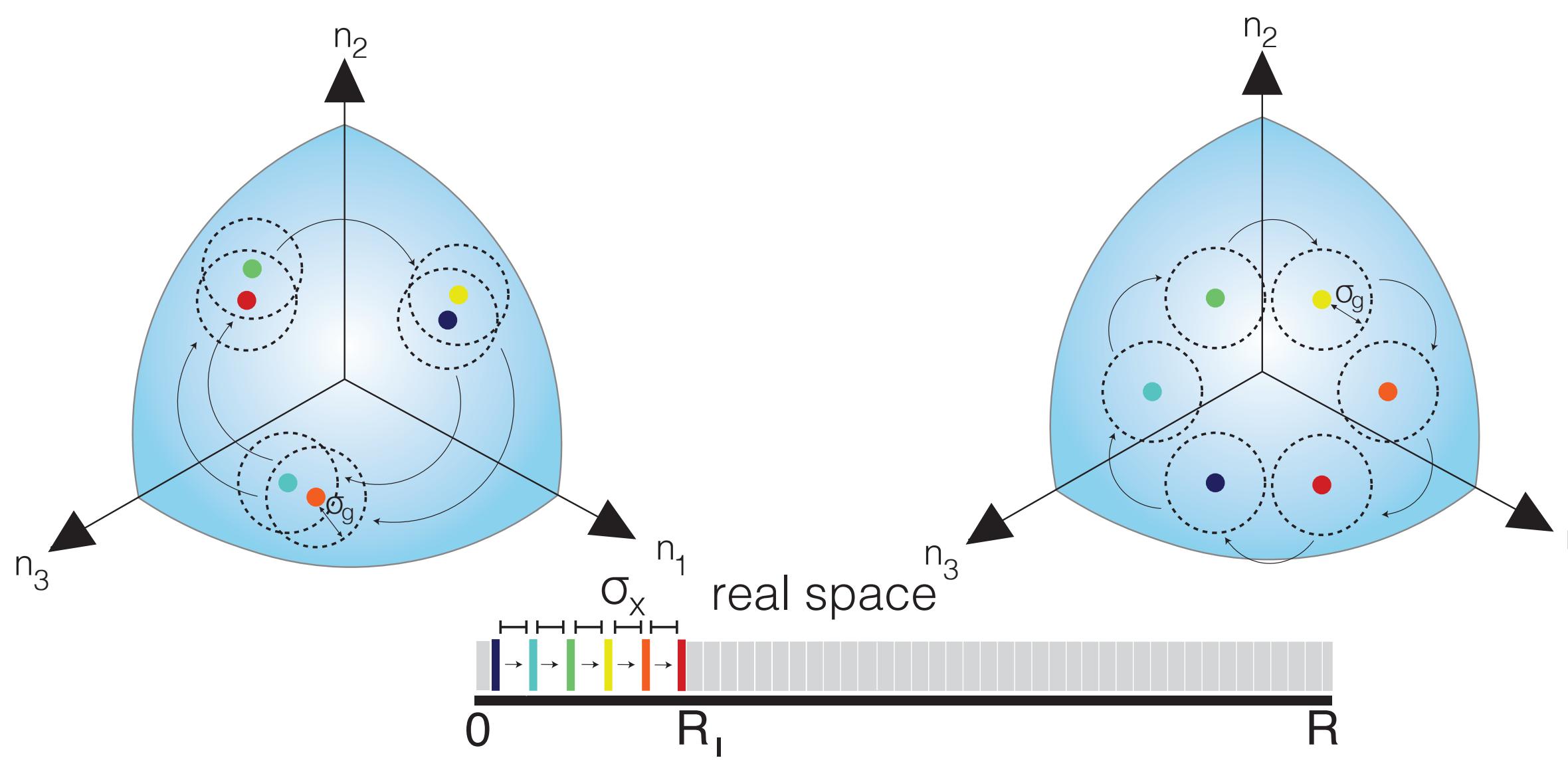
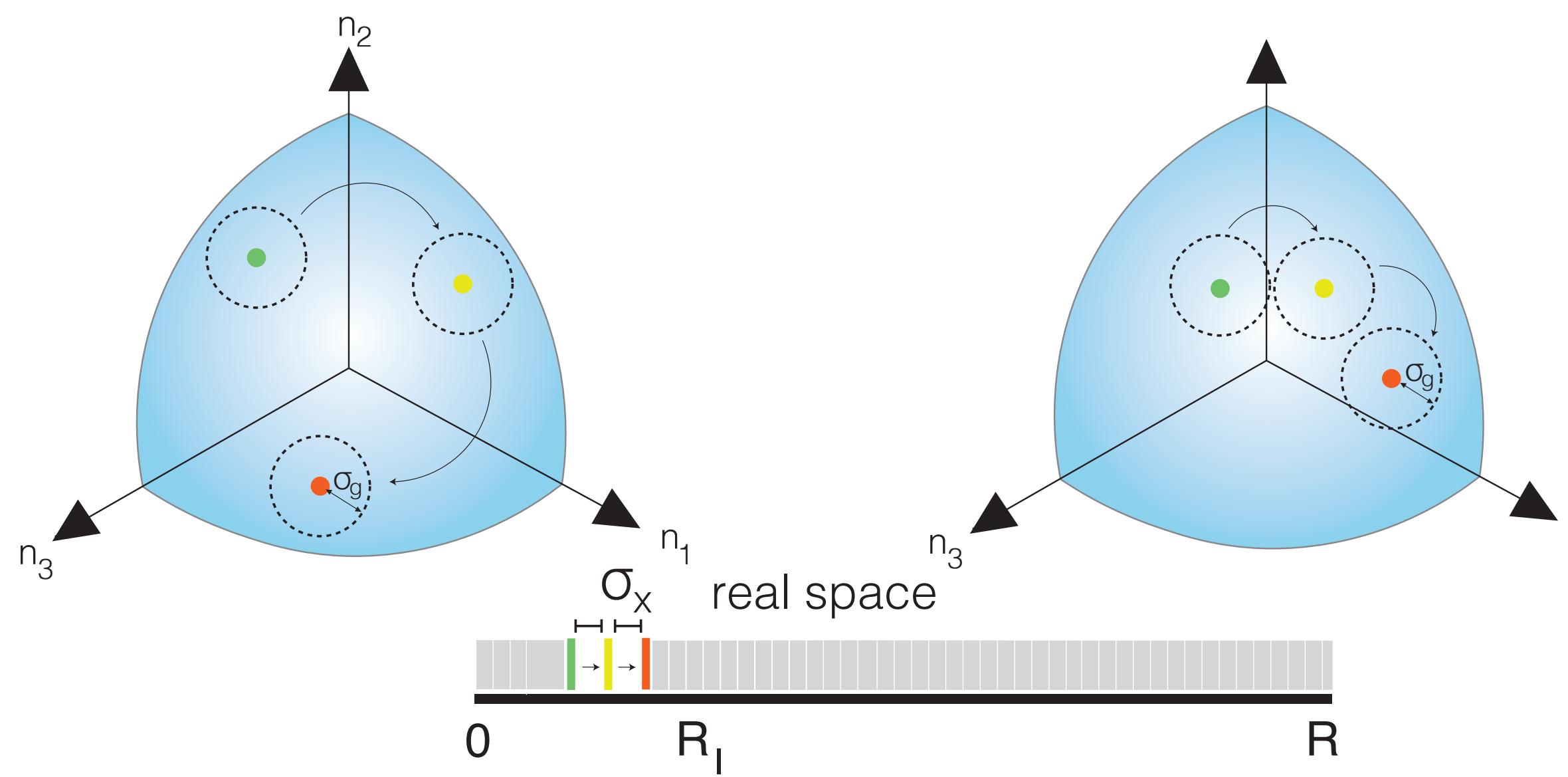
We can use these insights to formulate a self-supervised learning SSL problem

## Separation



We can use these insights to formulate a self-supervised learning SSL problem

less efficient use of neural space      **Capacity**      more efficient use of neural space

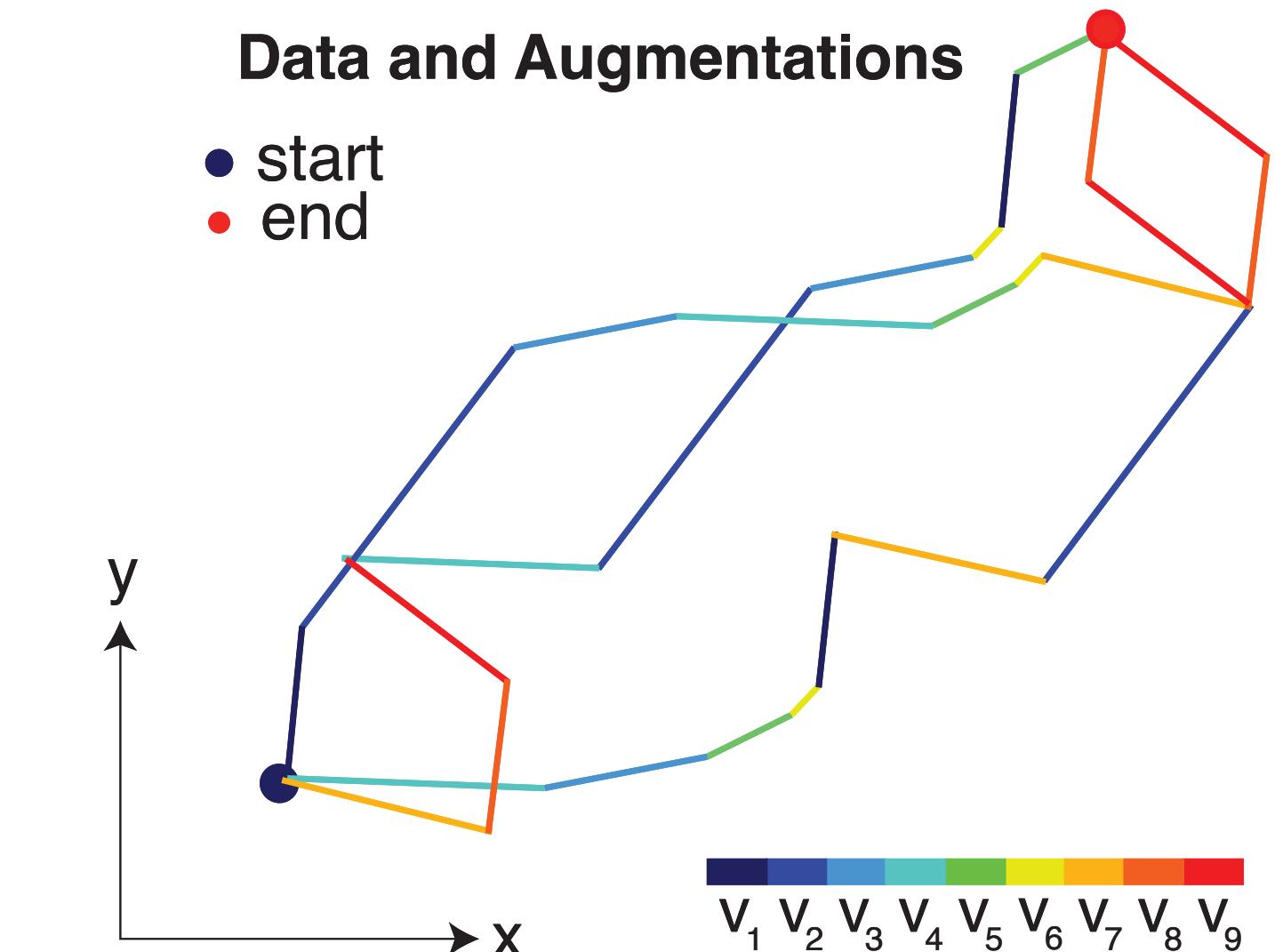


# Extending the self-supervised learning SSL problem to spatial navigation

To create a trajectory, we sample  $T$  velocities  $(\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_T)$ , with  $\mathbf{v}_t \sim_{i.i.d.} p(\mathbf{v})$

$$\{\pi_b\}_{b=1}^B$$

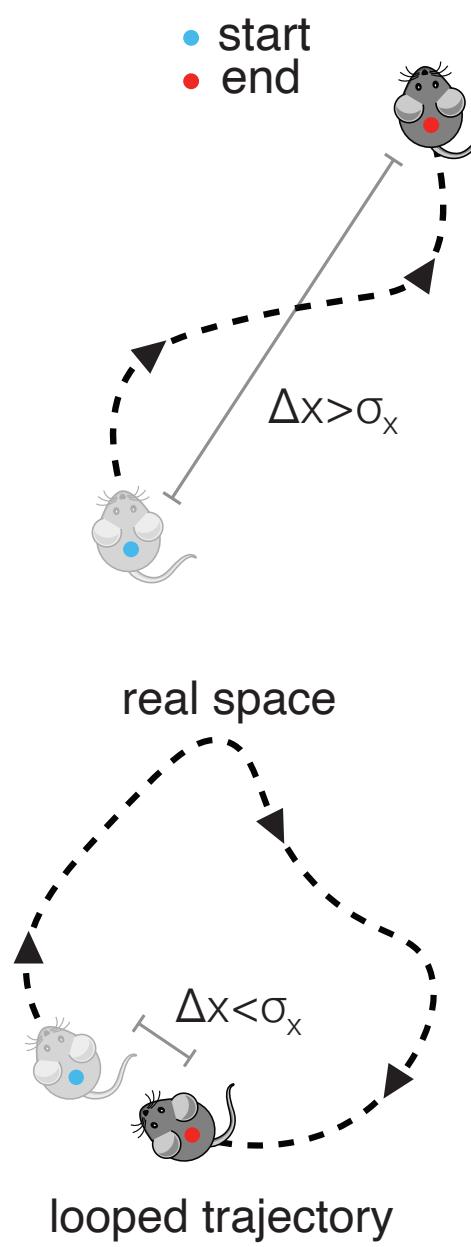
To create a batch, we create  $B$  random permutations:  $\pi_b : [T] \rightarrow [T]$



# Formulating a self-supervised learning SSL problem: loss functions

$$\mathcal{D}_{\text{gradient step}} = \left\{ (\mathbf{v}_{\pi_b(1)}, \mathbf{v}_{\pi_b(2)}, \dots, \mathbf{v}_{\pi_b(T)}), (\mathbf{g}_{\pi_b(1)}, \mathbf{g}_{\pi_b(2)}, \dots, \mathbf{g}_{\pi_b(T)}) \right\}_{b=1}^B$$

with shared initial state  $\mathbf{g}_0$



$$\mathcal{L}_{Sep} = \sum_{\substack{\forall \pi_b, \pi_{b'}, t, t': \\ \|\mathbf{x}_{\pi_{b'}(t)} - \mathbf{x}_{\pi_b(t')} \|_2 > \sigma_x}} \exp \left( - \frac{\|\mathbf{g}_{\pi_{b'}(t)} - \mathbf{g}_{\pi_b(t')}\|_2^2}{2\sigma_g^2} \right)$$

1 coarse grained bit of information about relative, and not absolute, spatial location

$$\mathcal{L}_{Inv} = \sum_{\substack{\forall \pi_b, \pi_{b'}, t, t': \\ \|\mathbf{x}_{\pi_{b'}(t)} - \mathbf{x}_{\pi_b(t')}\|_2 < \sigma_x}} \left\| \mathbf{g}_{\pi_b(t)} - \mathbf{g}_{\pi_{b'}(t')} \right\|_2^2$$

Regularization

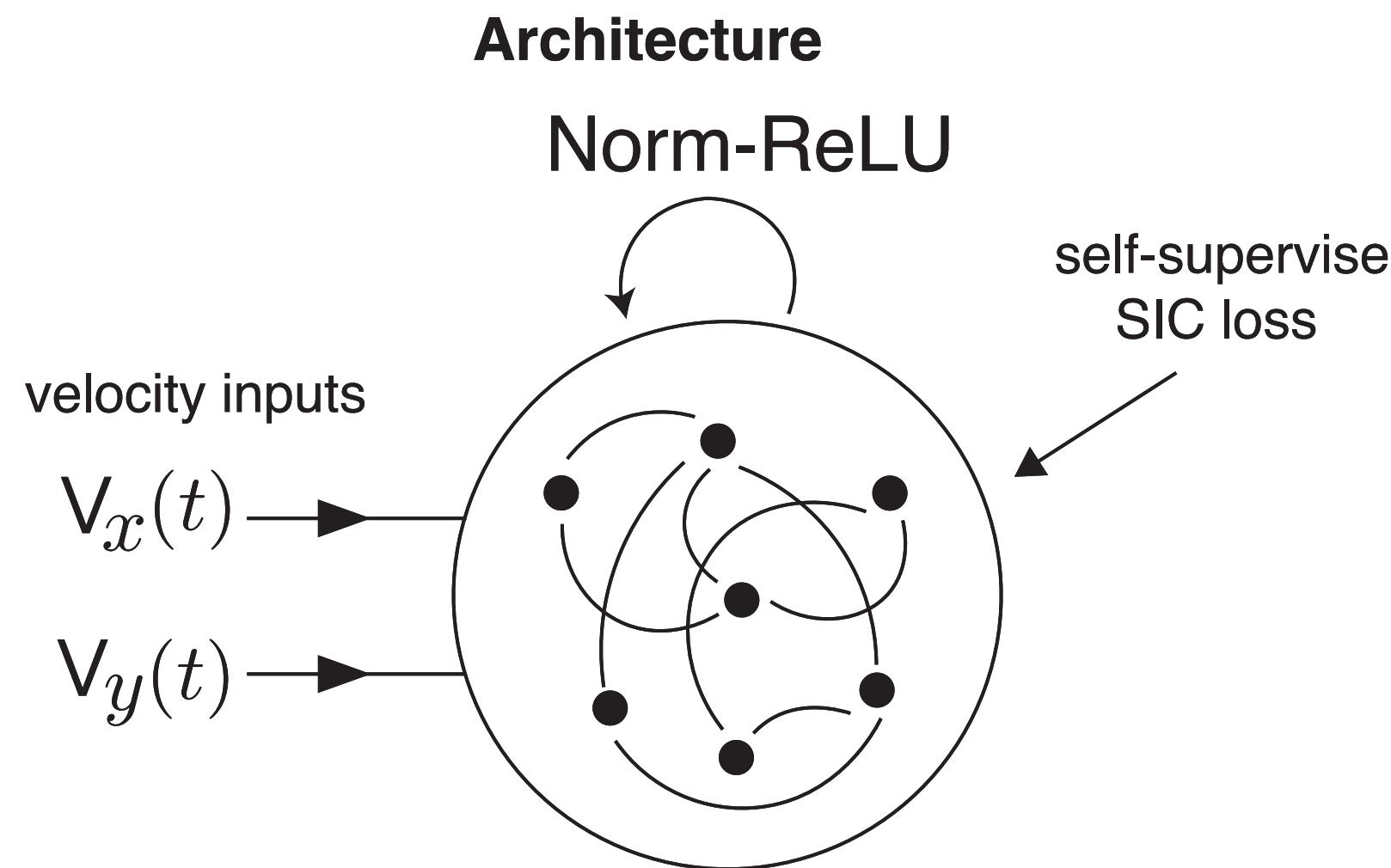
$$\mathcal{L}_{Cap} = - \left\| \frac{1}{BT} \sum_{\pi_b, t} \mathbf{g}_{\pi_b(t)} \right\|_2^2$$

Regularization

$$\mathcal{L}_{ConIso} \stackrel{\text{def}}{=} \mathbb{V} \left[ \left\{ \frac{\|\mathbf{g}_t - \mathbf{g}_{t-1}\|}{\|\mathbf{v}_t\|} \right\}_{t: 0 < \|\mathbf{v}_t\| < \sigma_x} \right]$$

Contrast with supervised approaches that provide absolute spatial information at all times

# Formulating a self-supervised learning SSL problem: architecture



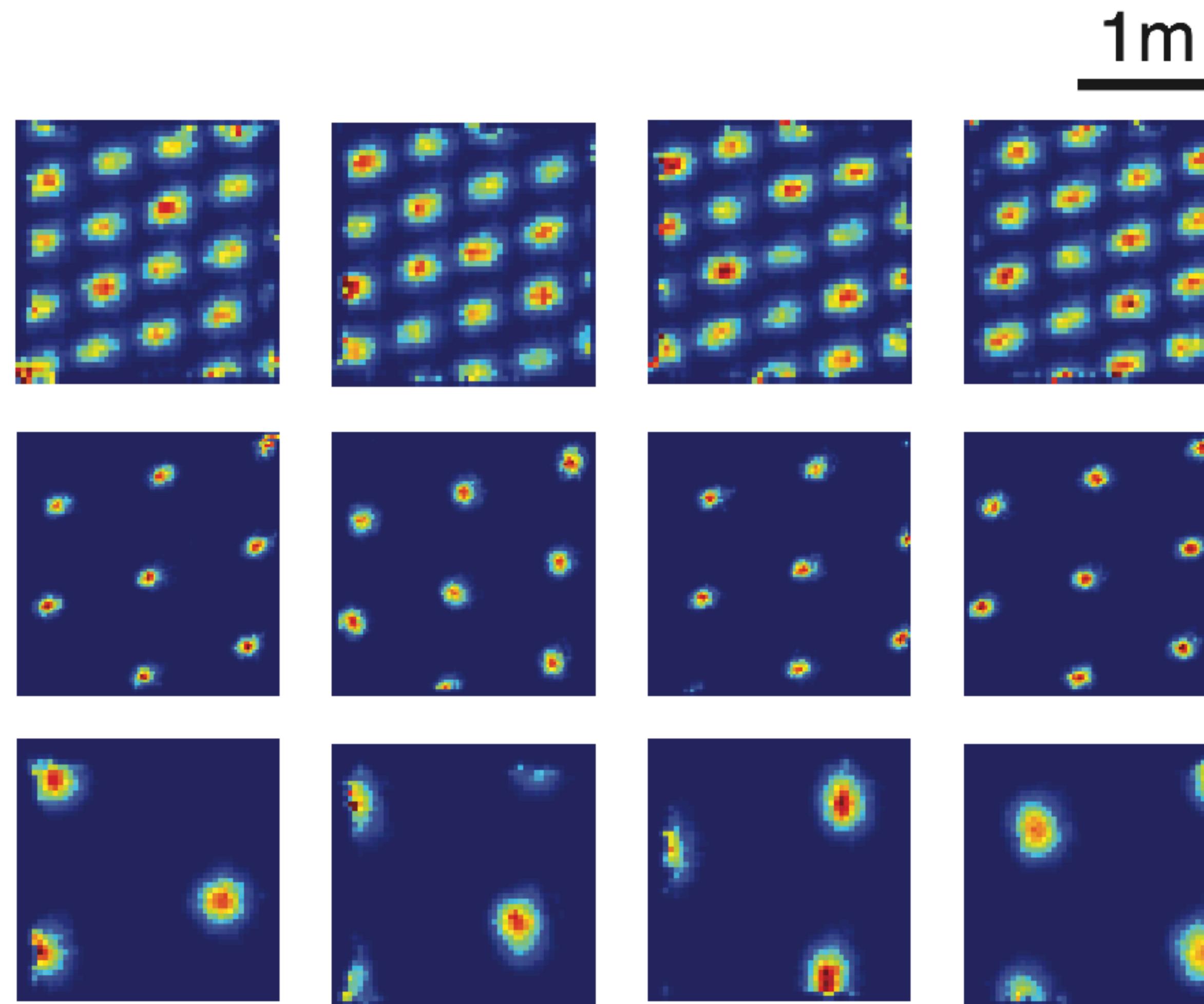
$$W(\mathbf{v}_t) = MLP(\mathbf{v}_t)$$

$$\mathbf{g}_t = \sigma(W(\mathbf{v}_t) \mathbf{g}_{t-1})$$

$$\sigma(\cdot) = Norm(ReLU(\cdot)) = ReLU(\cdot) / \|ReLU(\cdot)\|$$

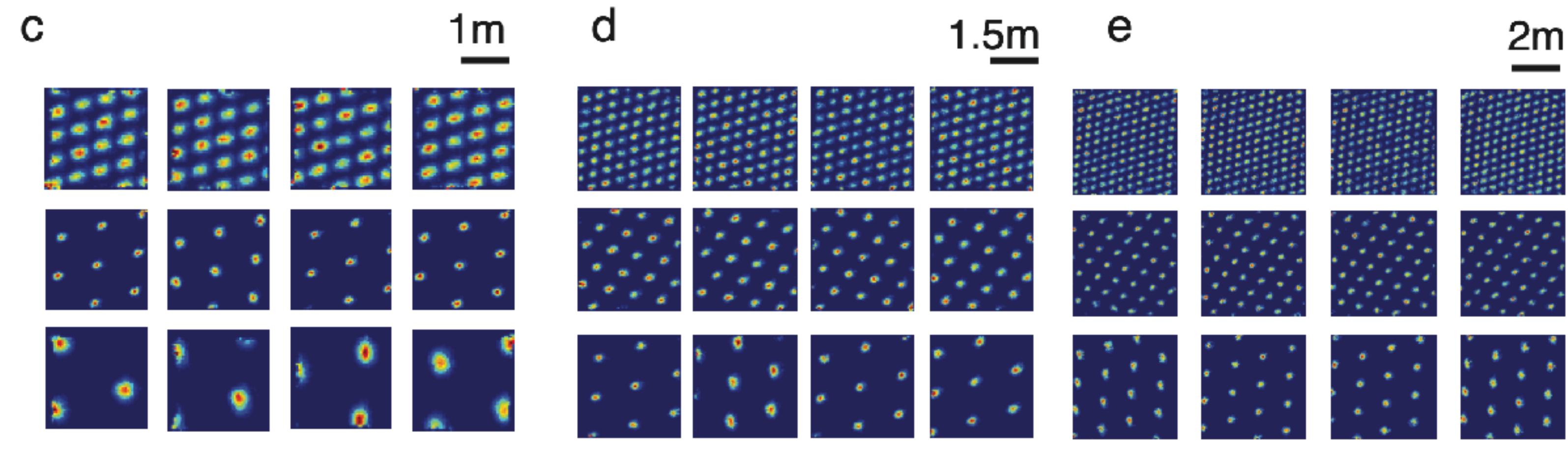
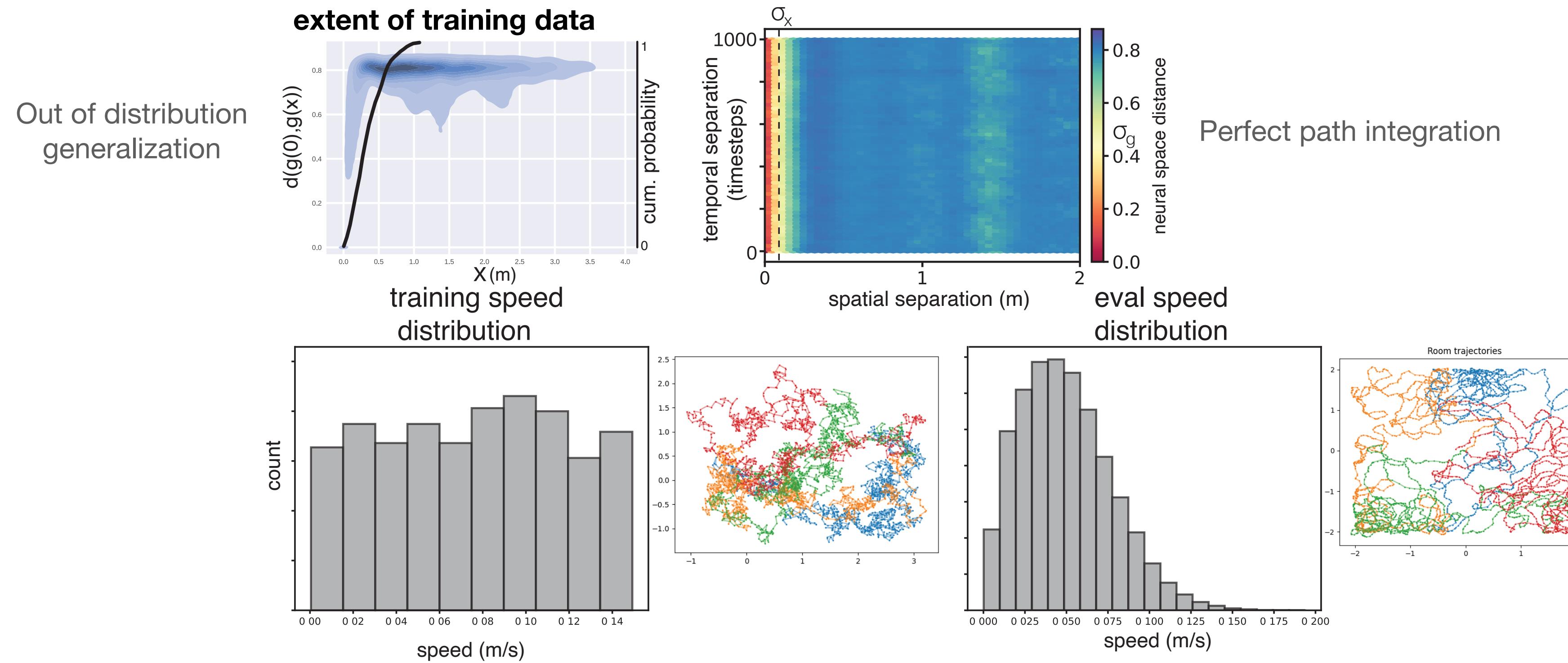
Normalization of neural population activity: prevent trivial solutions often found by contrastive SSL

Result: It is *possible* to get multi-periodic grid-like solutions!



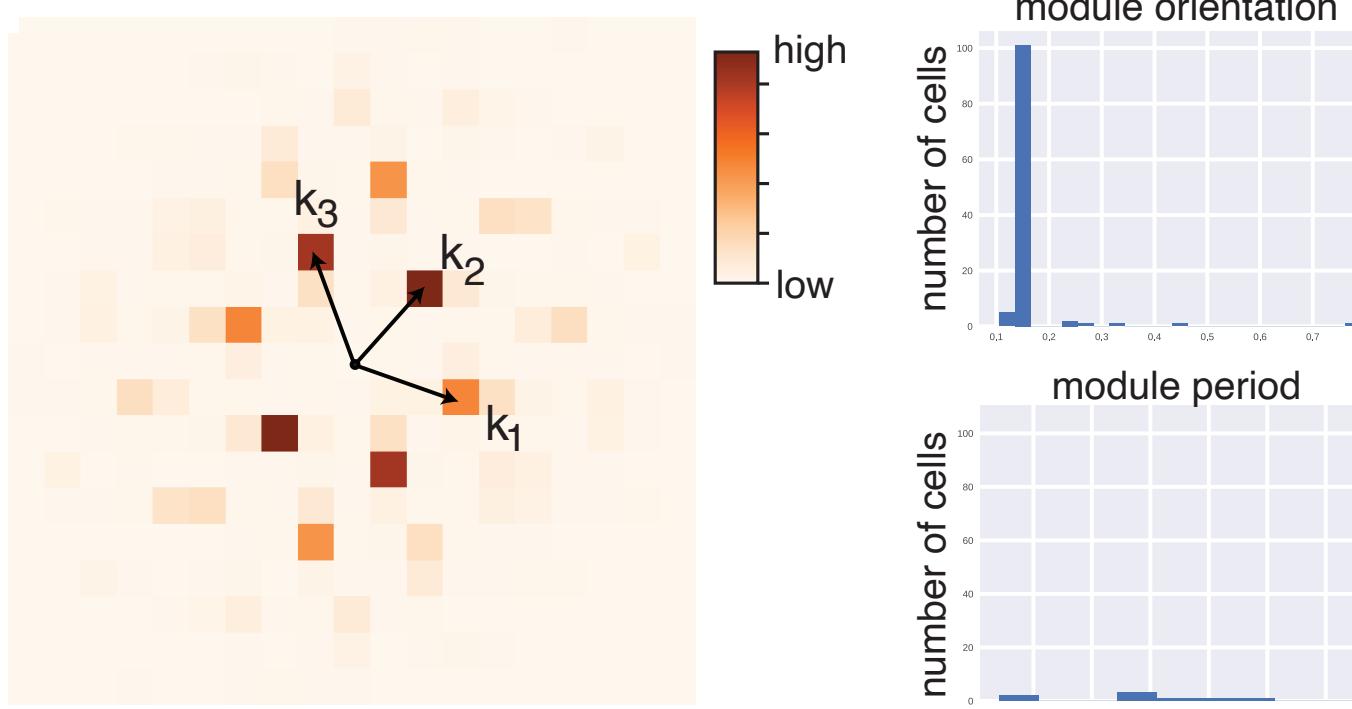
12 cells from a 128 neuron RNN

# Solutions generalize to larger environments and distinct input statistics without any additional training

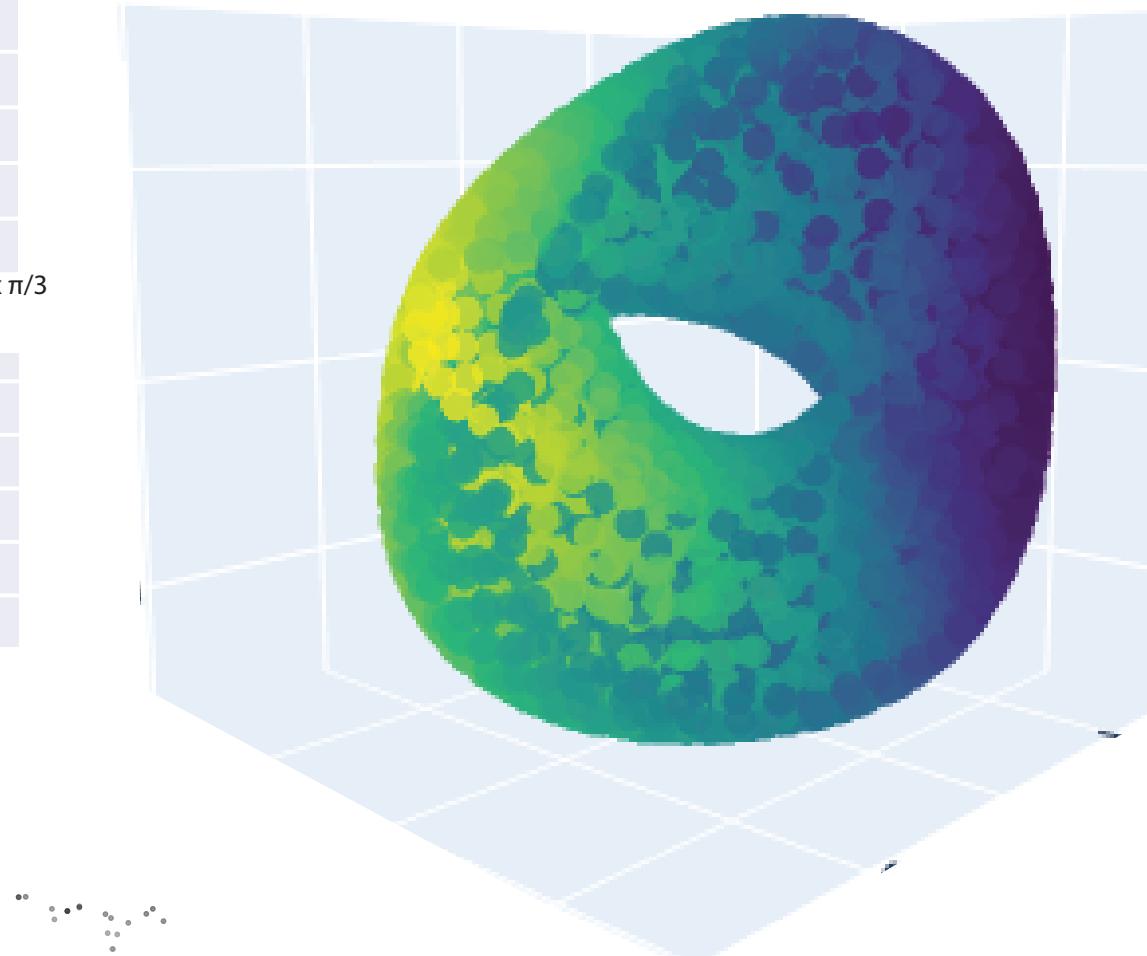


# Dissecting a single module shows key properties of grid cells

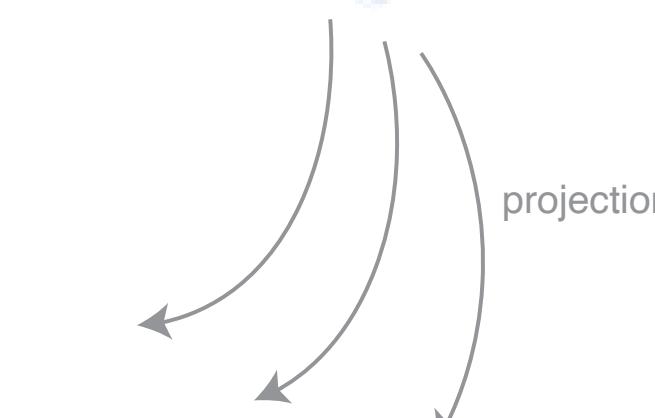
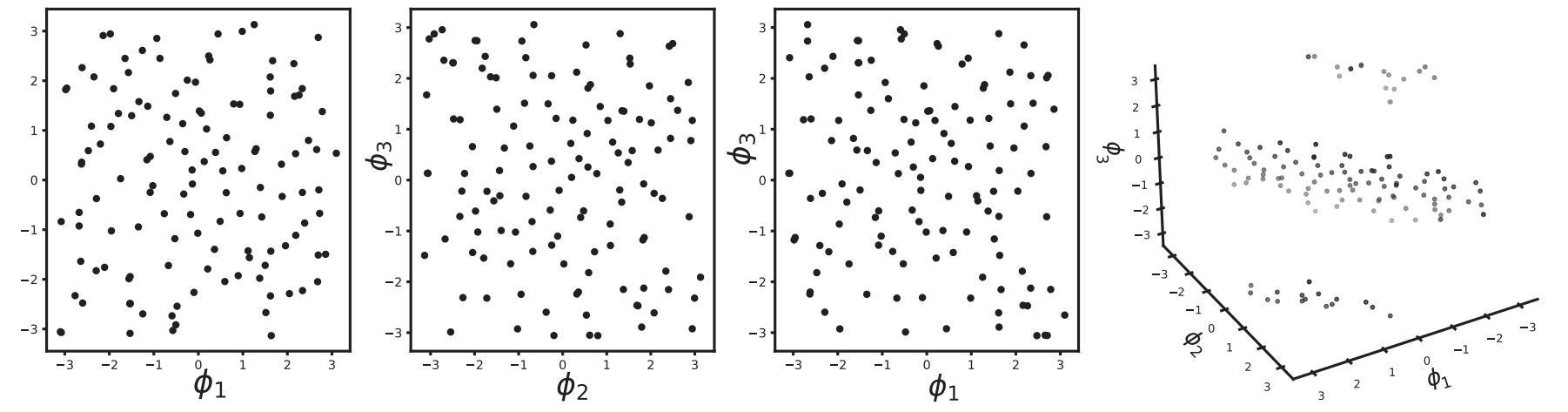
## mean fourier power



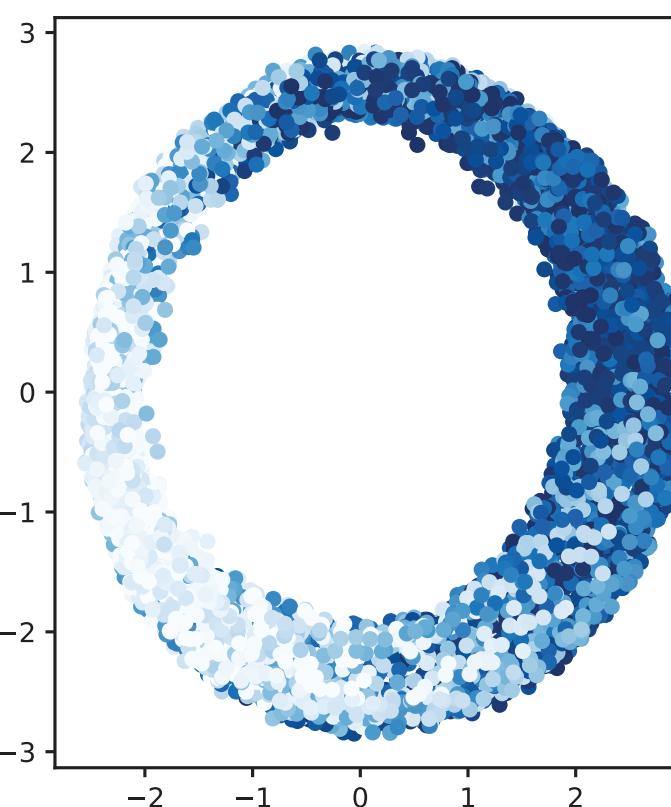
## toroidal state space



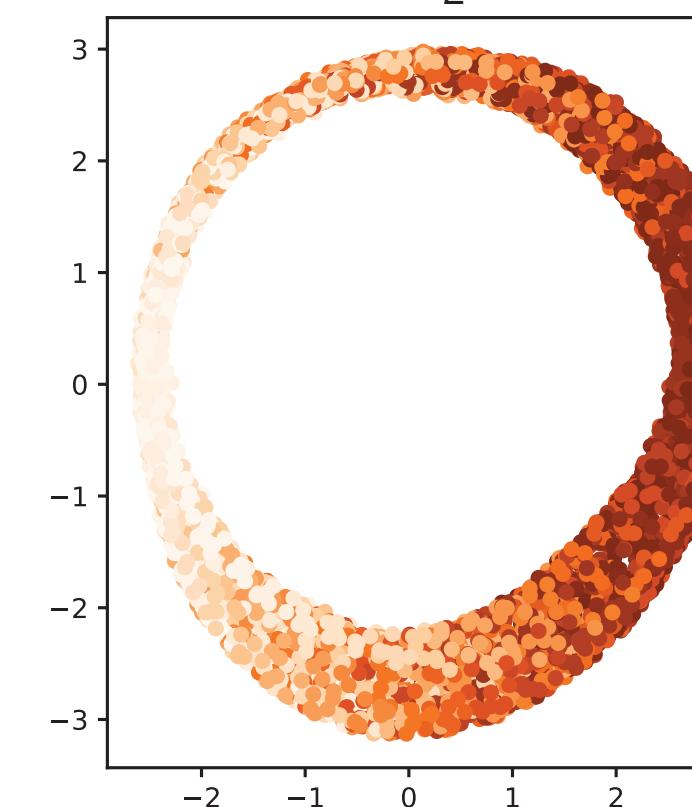
## phase coverage



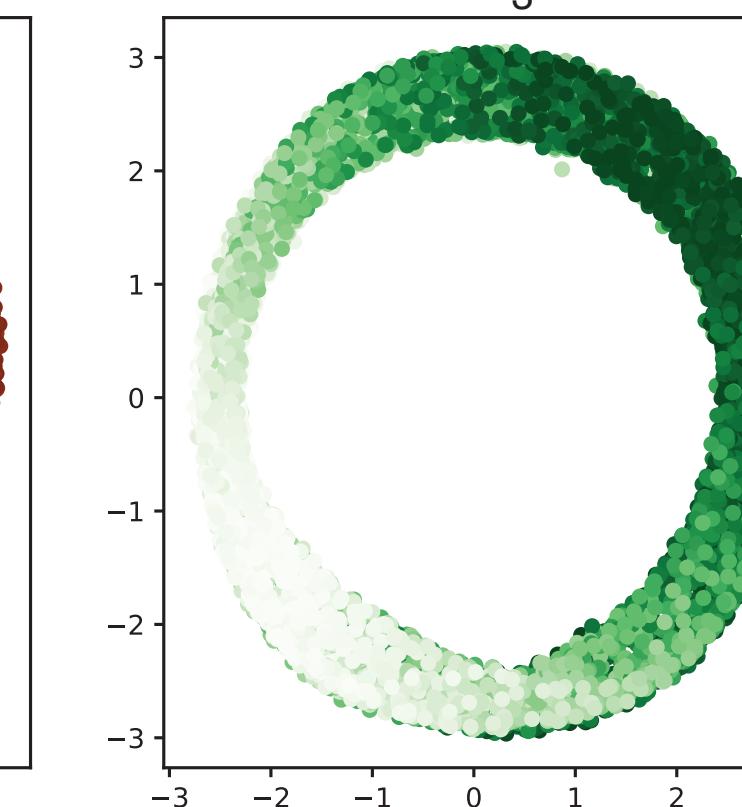
## $k_1$



## $k_2$



## $k_3$



Gardner et al Nature (2022)

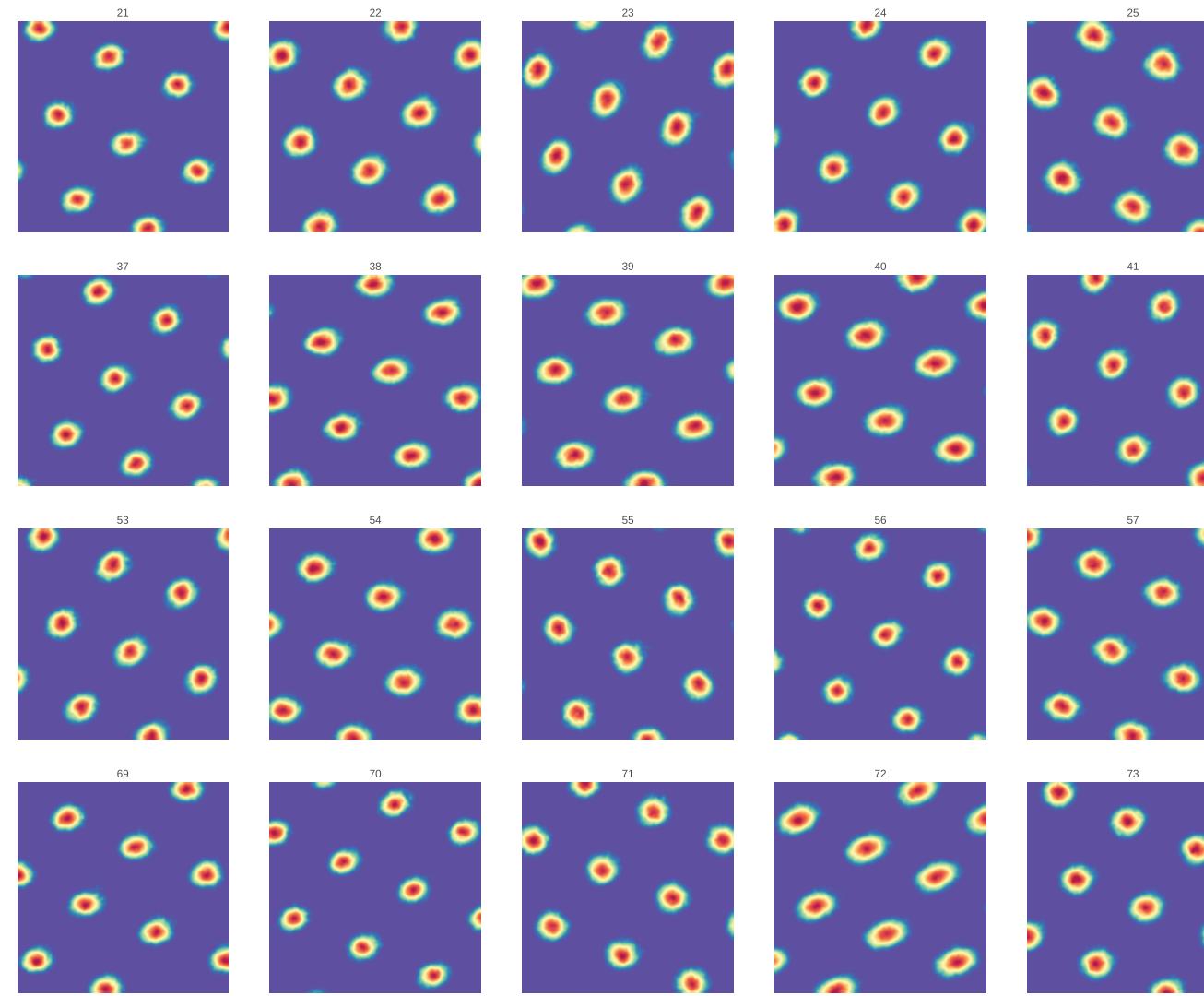
Signature of high dimensional  
'twisted torus' topology!

Sorscher\*, Mel\* et al (2023)

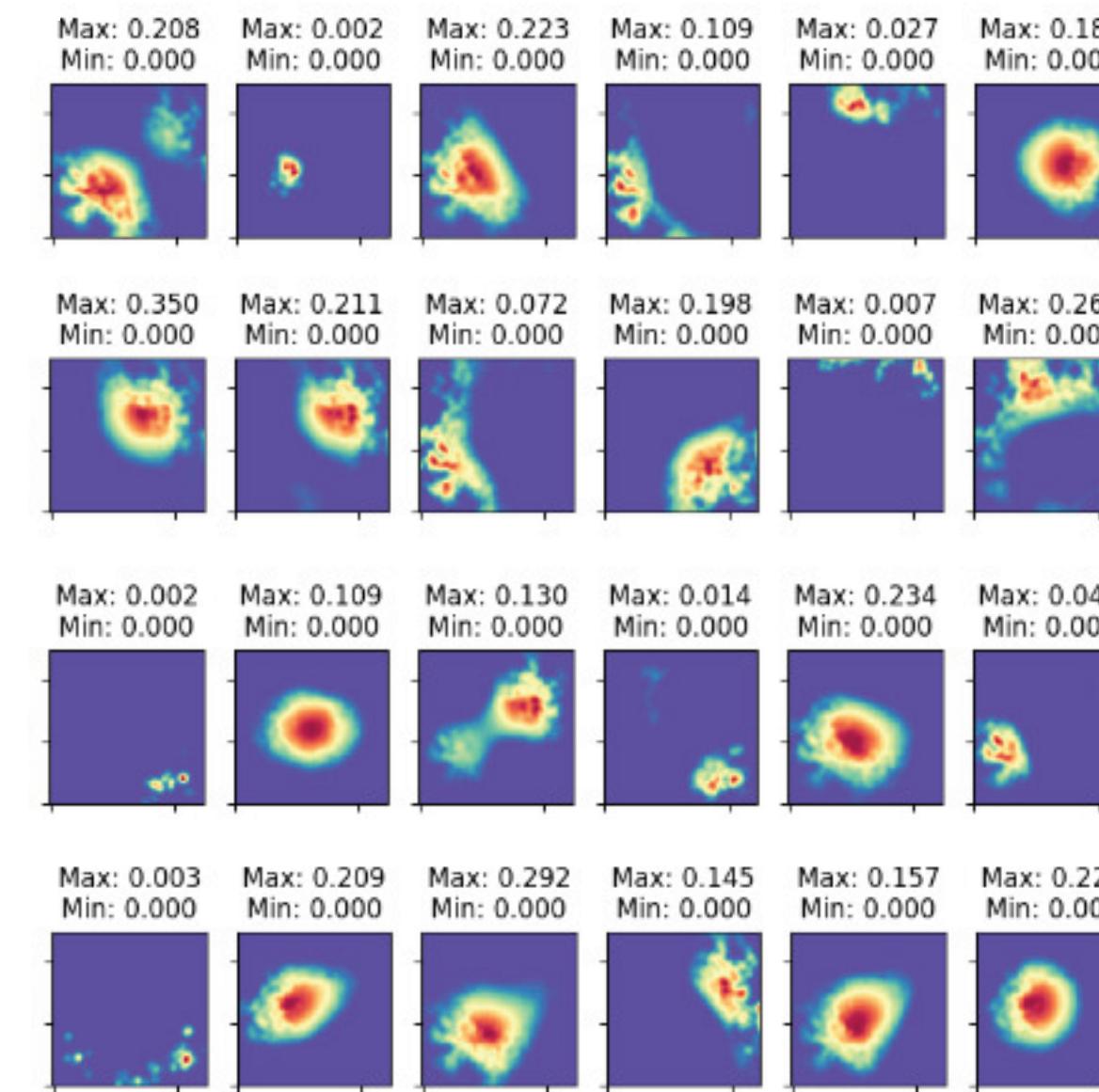
# When does a multi-periodic solution NOT appear?

Still see 1 perfect module of grids!

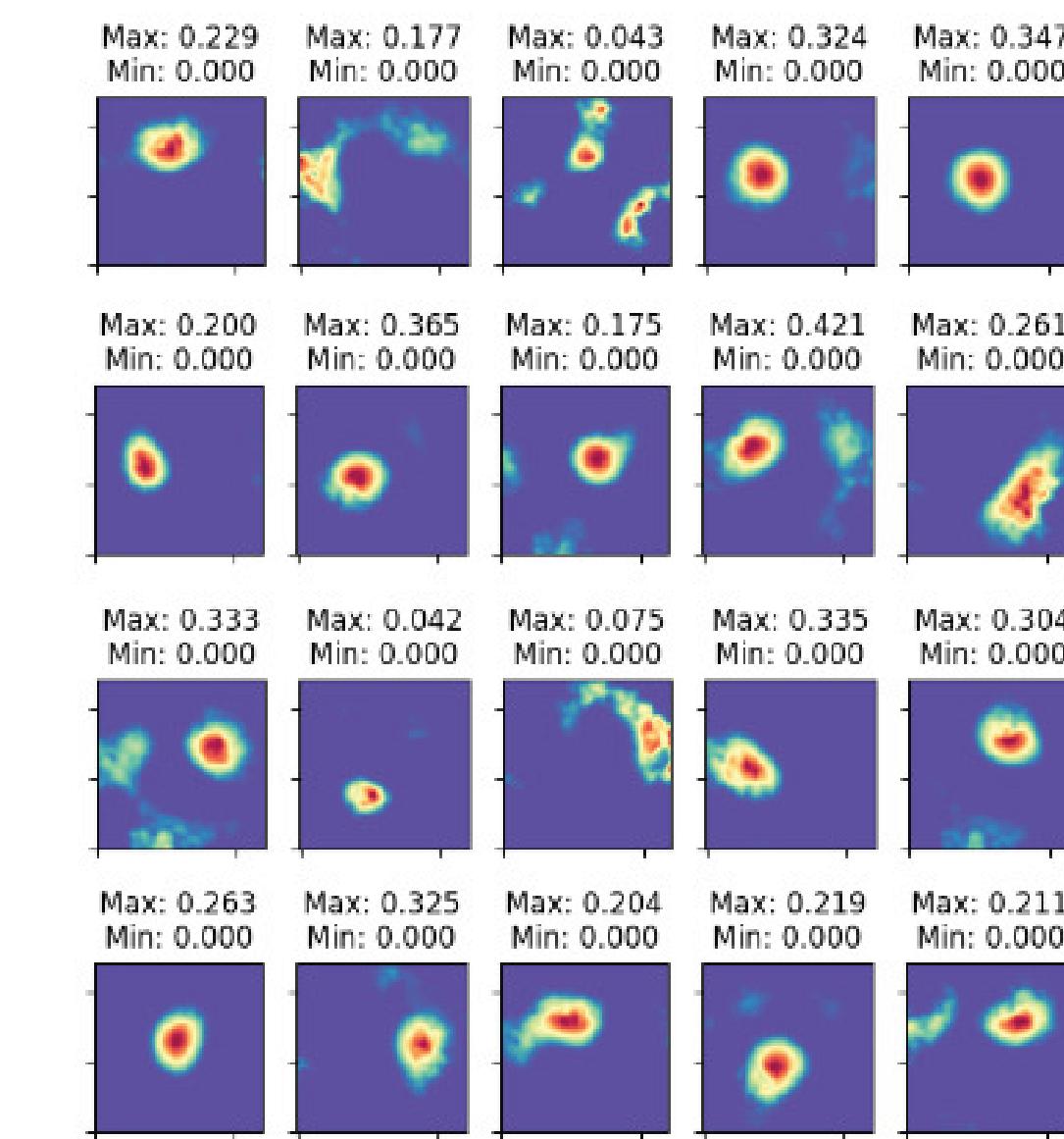
capacity loss ablation



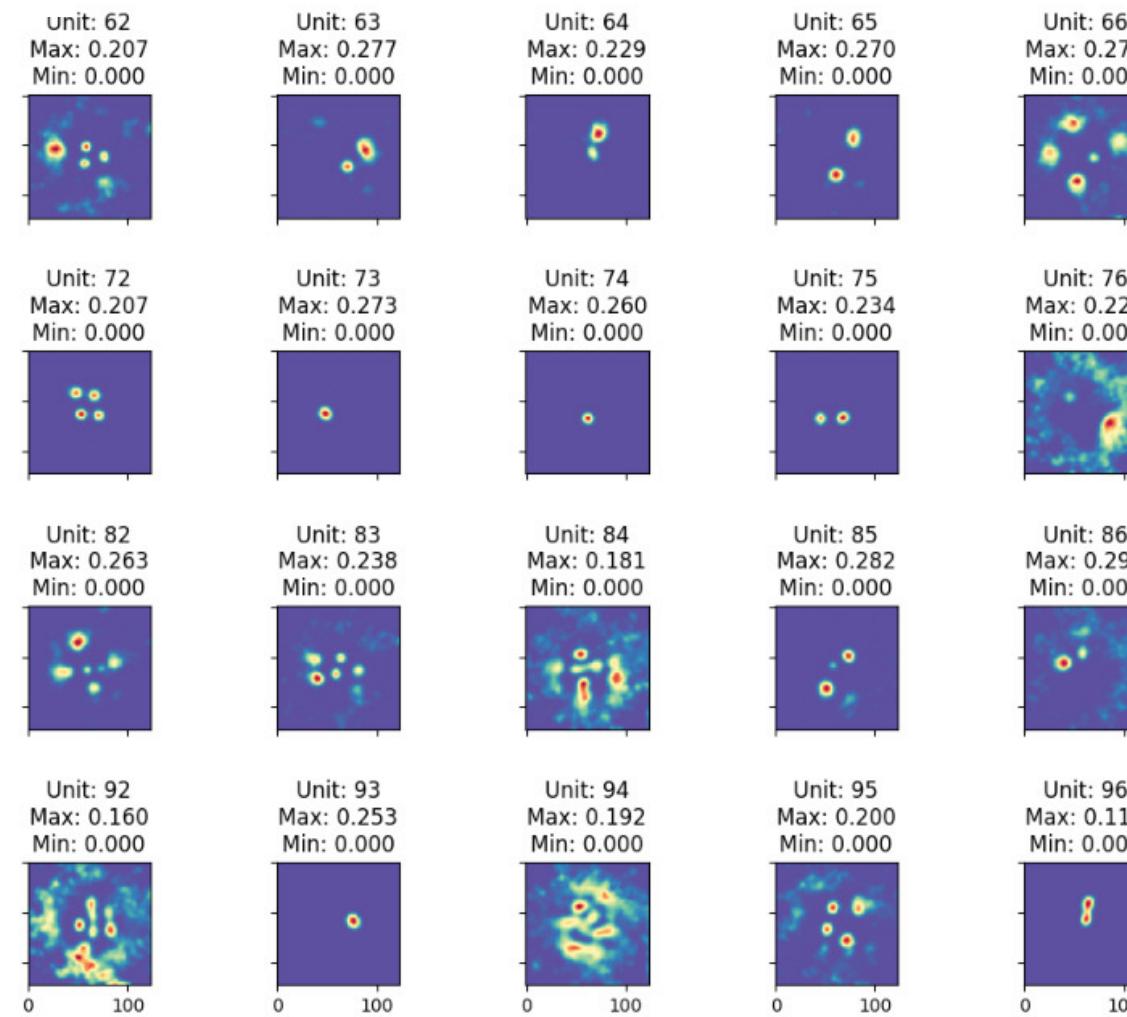
capacity loss ablation +  $\sigma_g=0.1$



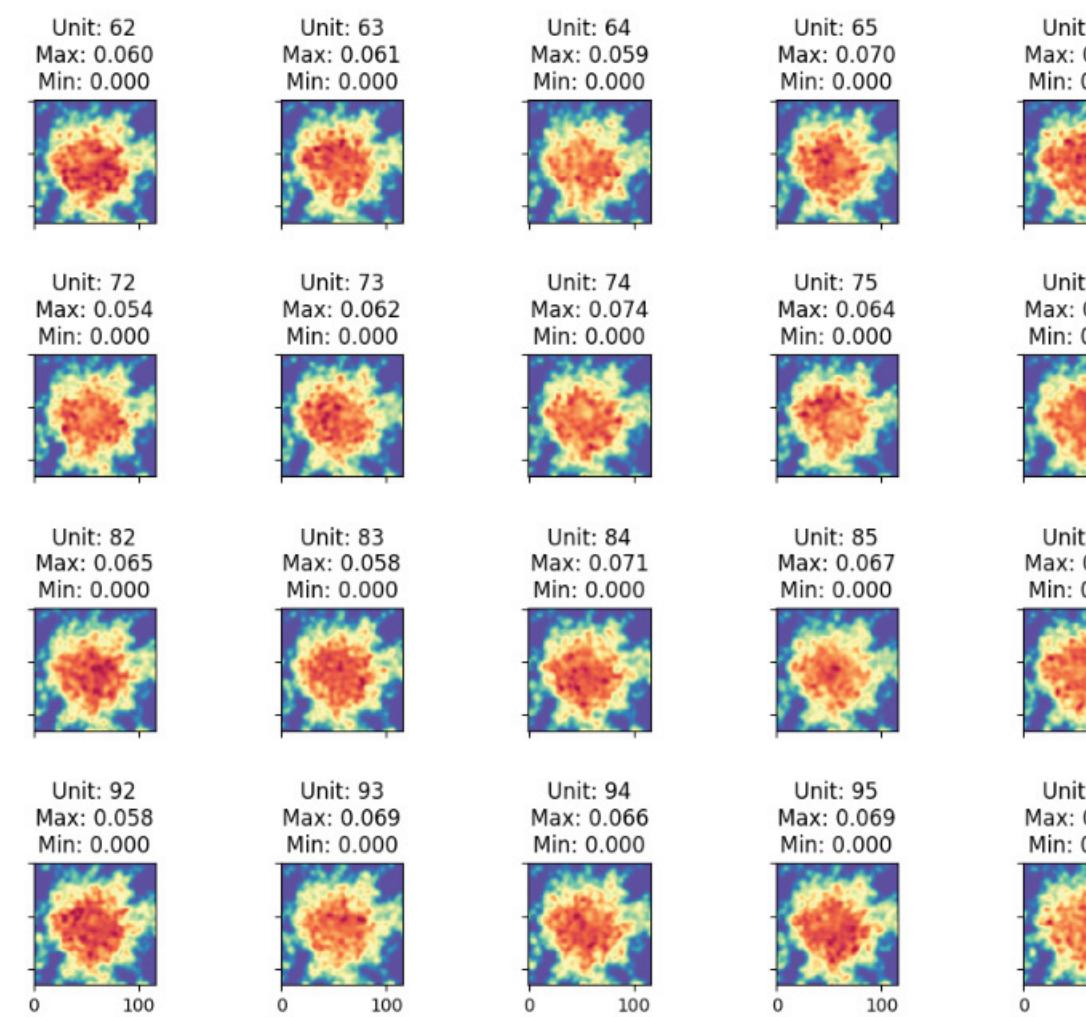
capacity loss ablation +  $\sigma_g=0.2$



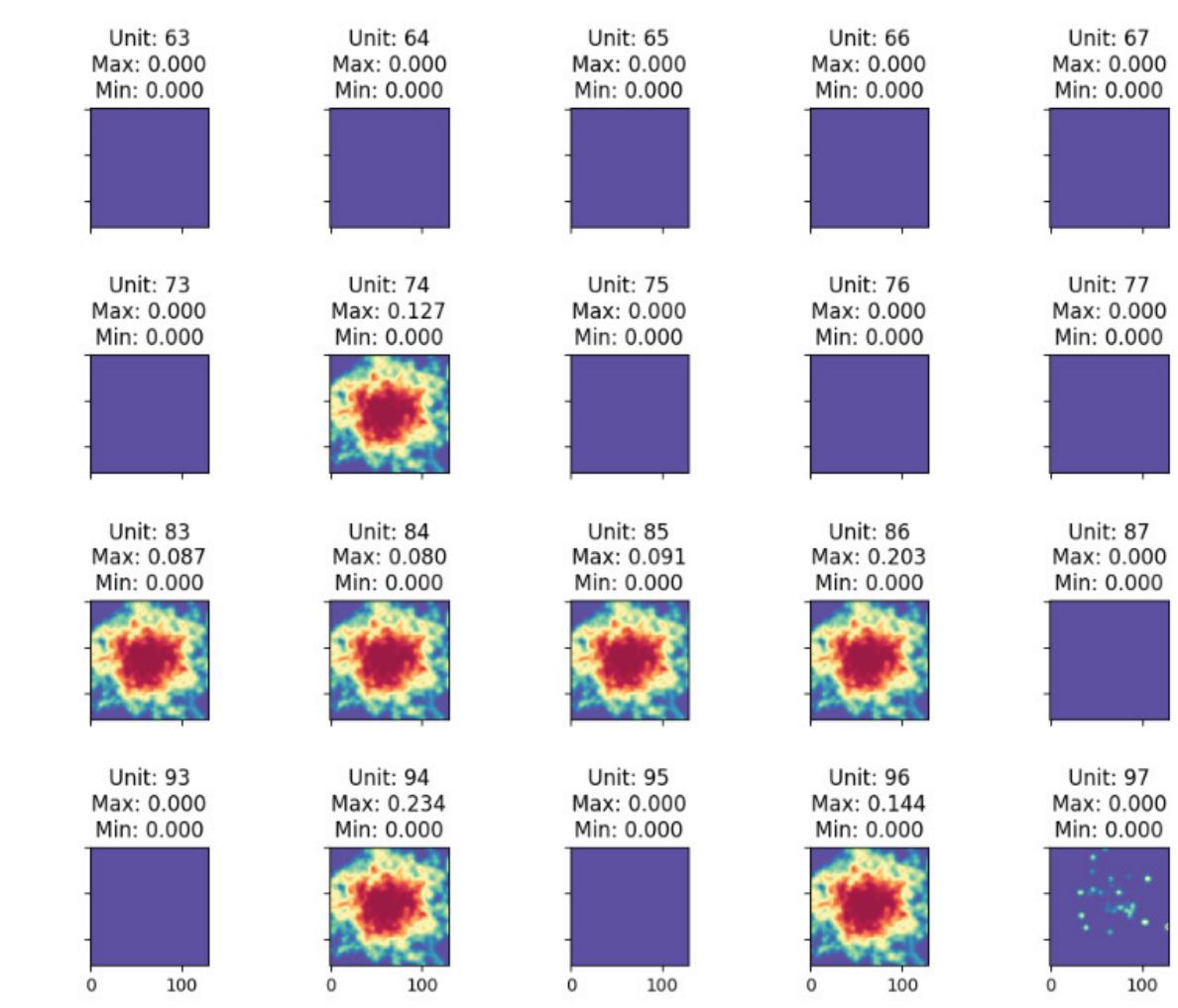
trajectory permutations ablation

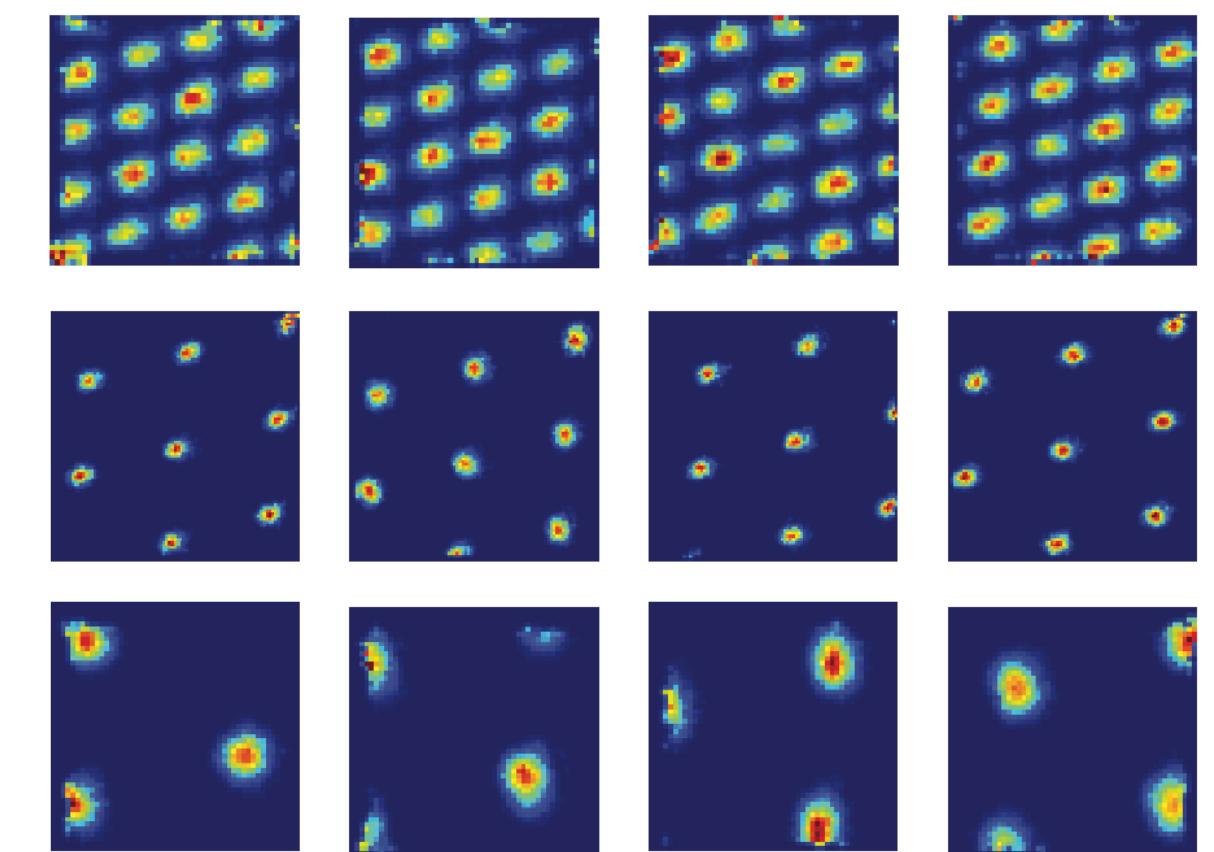
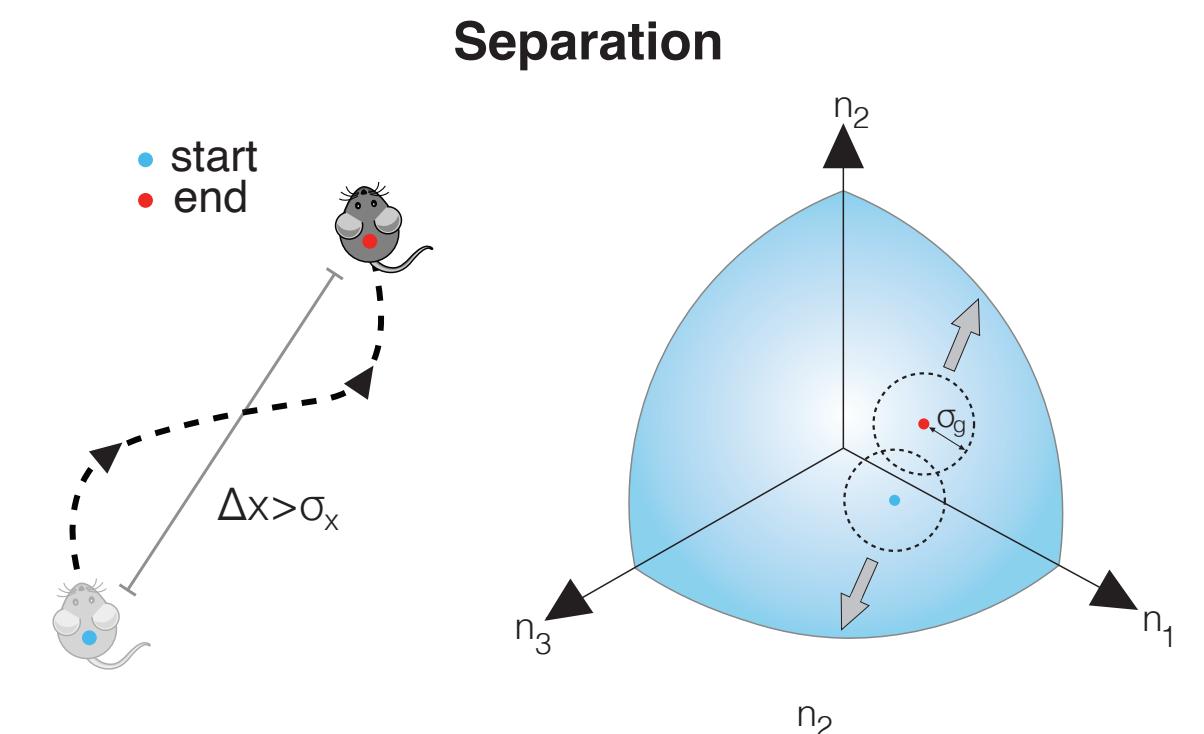
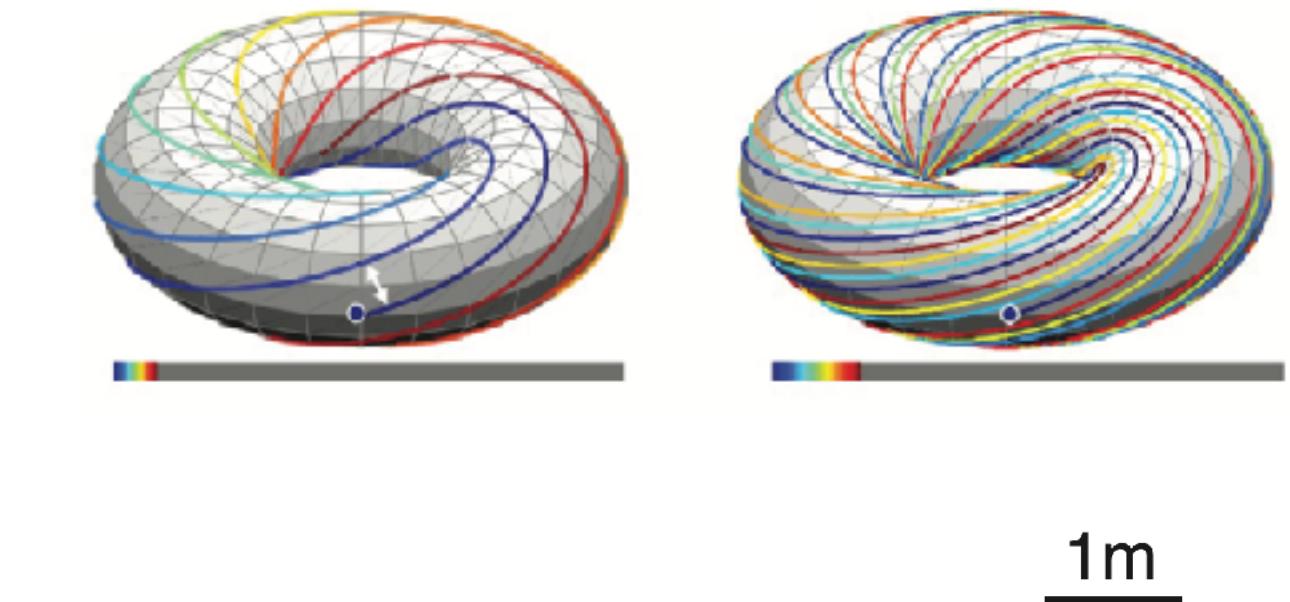
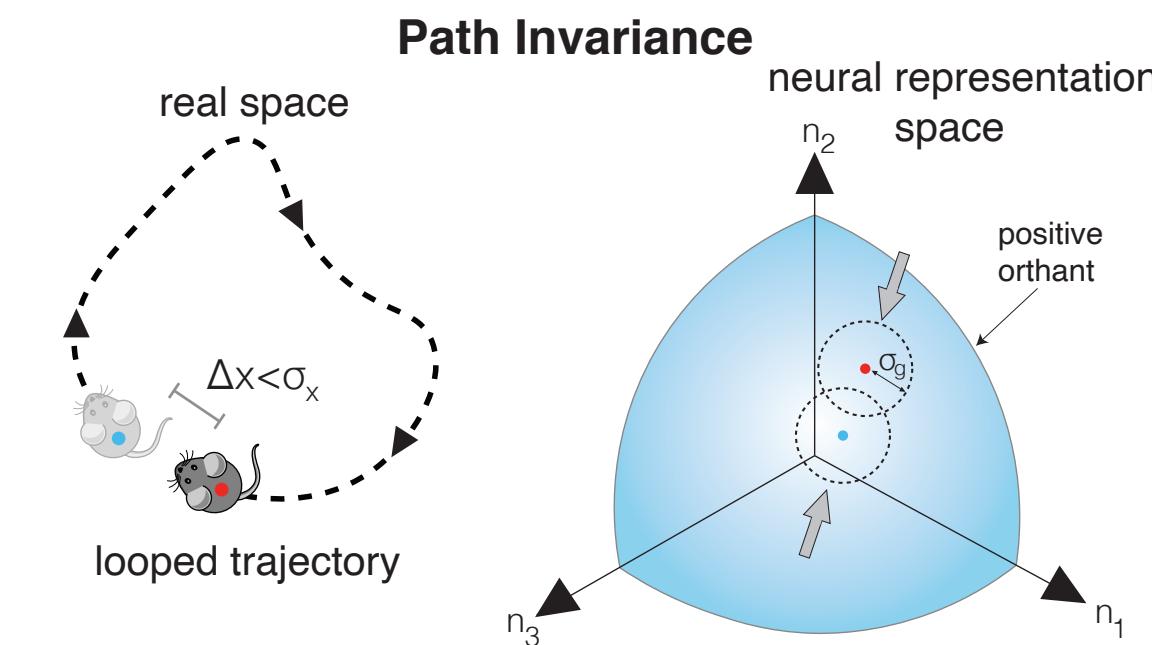
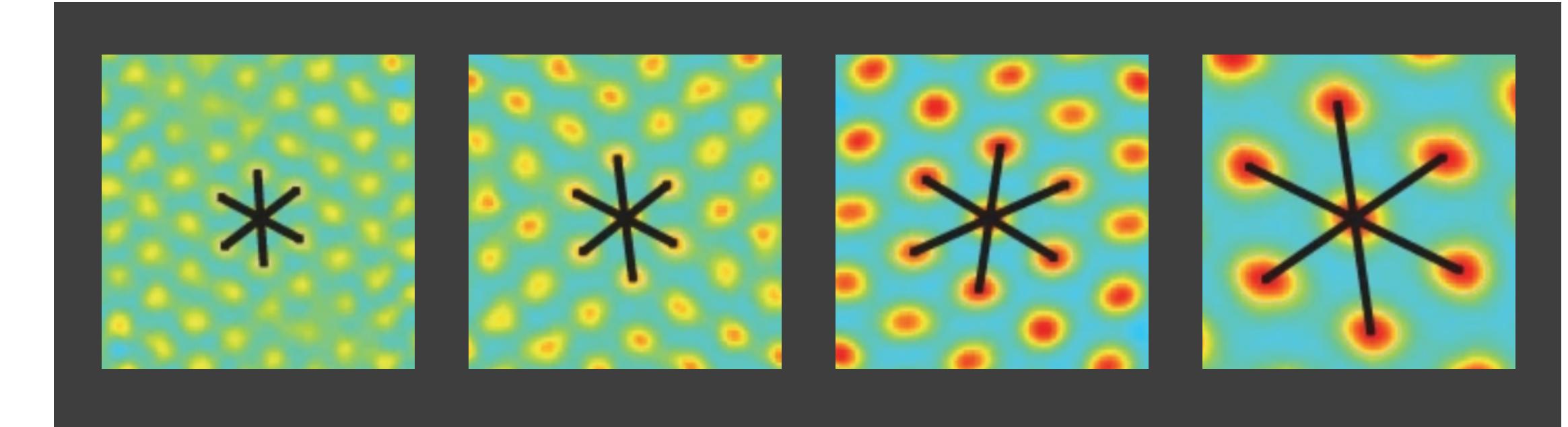
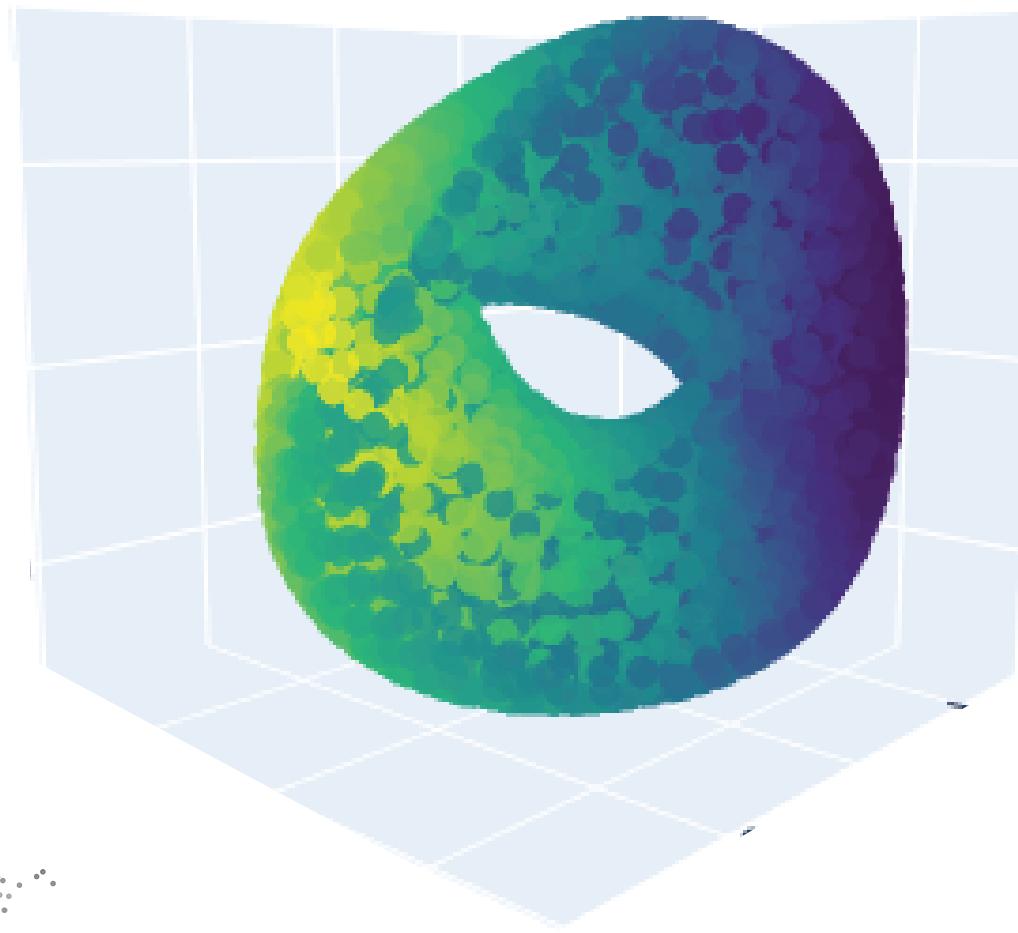
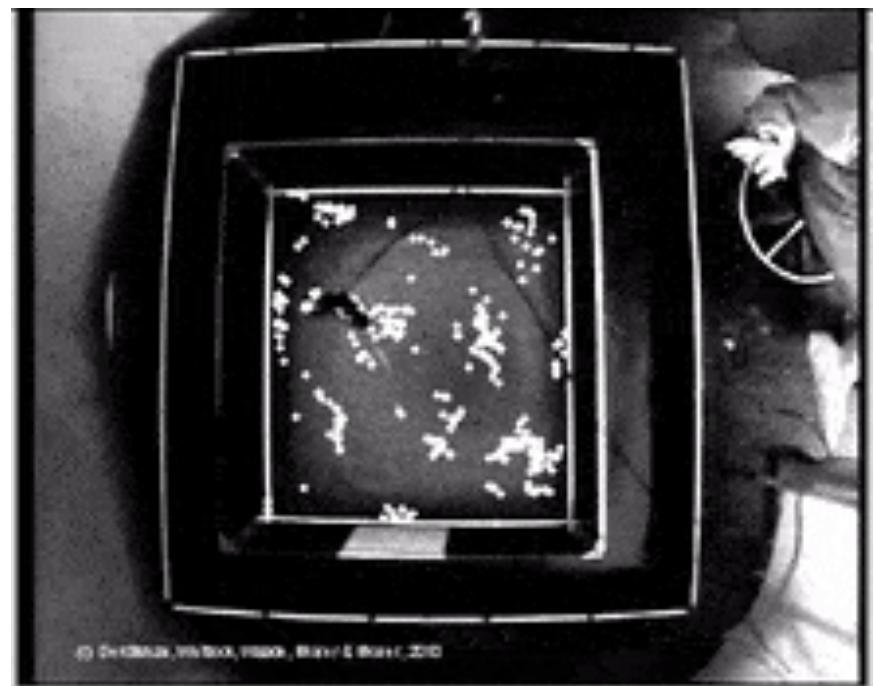


path invariance loss ablation



separation loss ablation





Thank you!

Mikail Khona @KhonaMikail  
([mikail@mit.edu](mailto:mikail@mit.edu))

Rylan Schaeffer @RylanSchaeffer  
([rylanschaeffer@gmail.com](mailto:rylanschaeffer@gmail.com))

Self-Supervised Learning of Representations for Space Generates Multi-Modular Grid Cells, NeurIPS 2023

